

# **A WiFS Imagery: Processing & Automated Feature Extraction**

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**JACIE 2007**



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# Outline

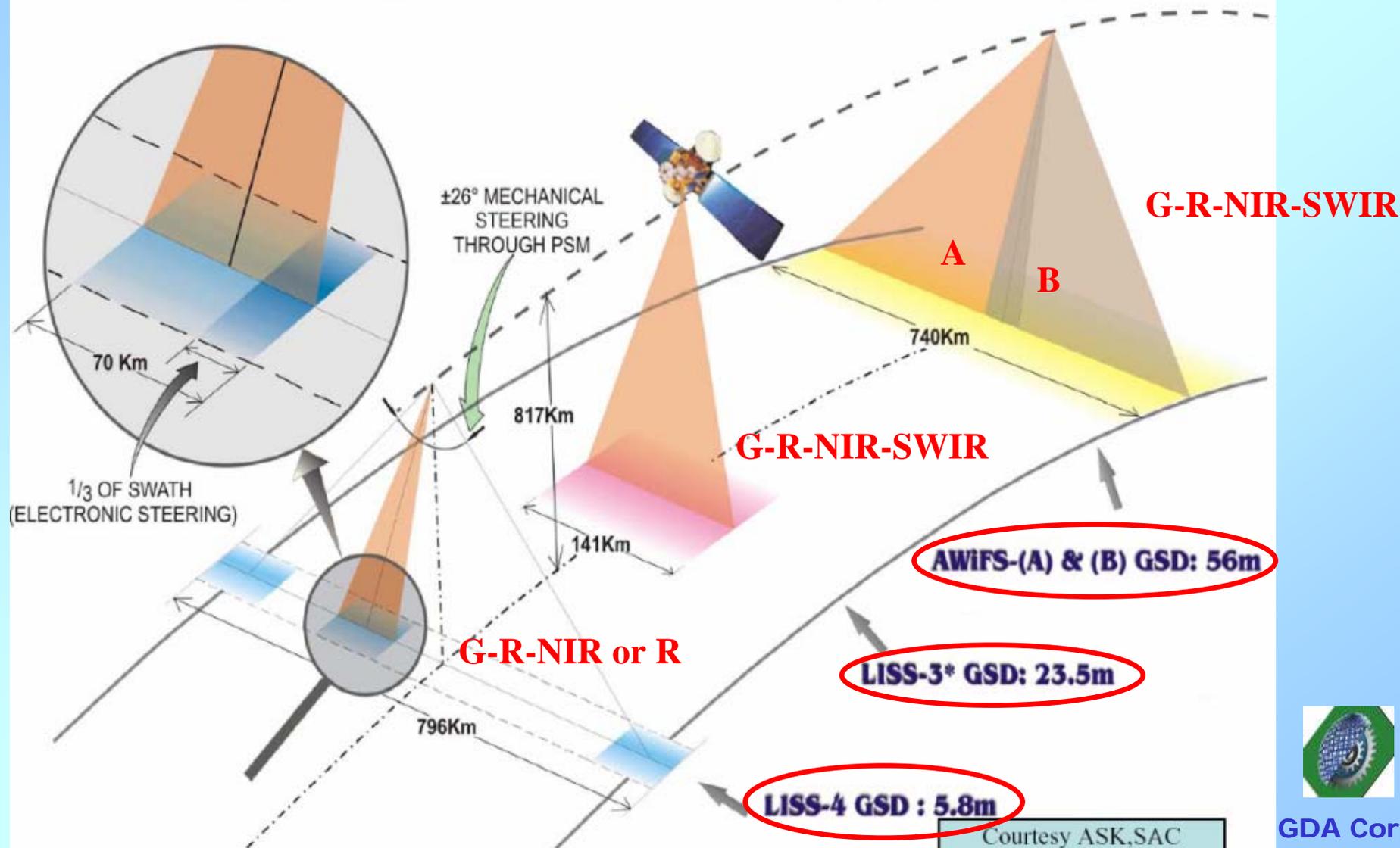
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- **AWiFS Overview**
- **AWiFS Surface Reflectance Calibration**
- **Cloud Detection in AWiFS -- CASA-AWiFS**
- **Feature Detection in AWiFS: Water, Snow/Ice**
- **GDA Future R&D Plans**
- **Questions**



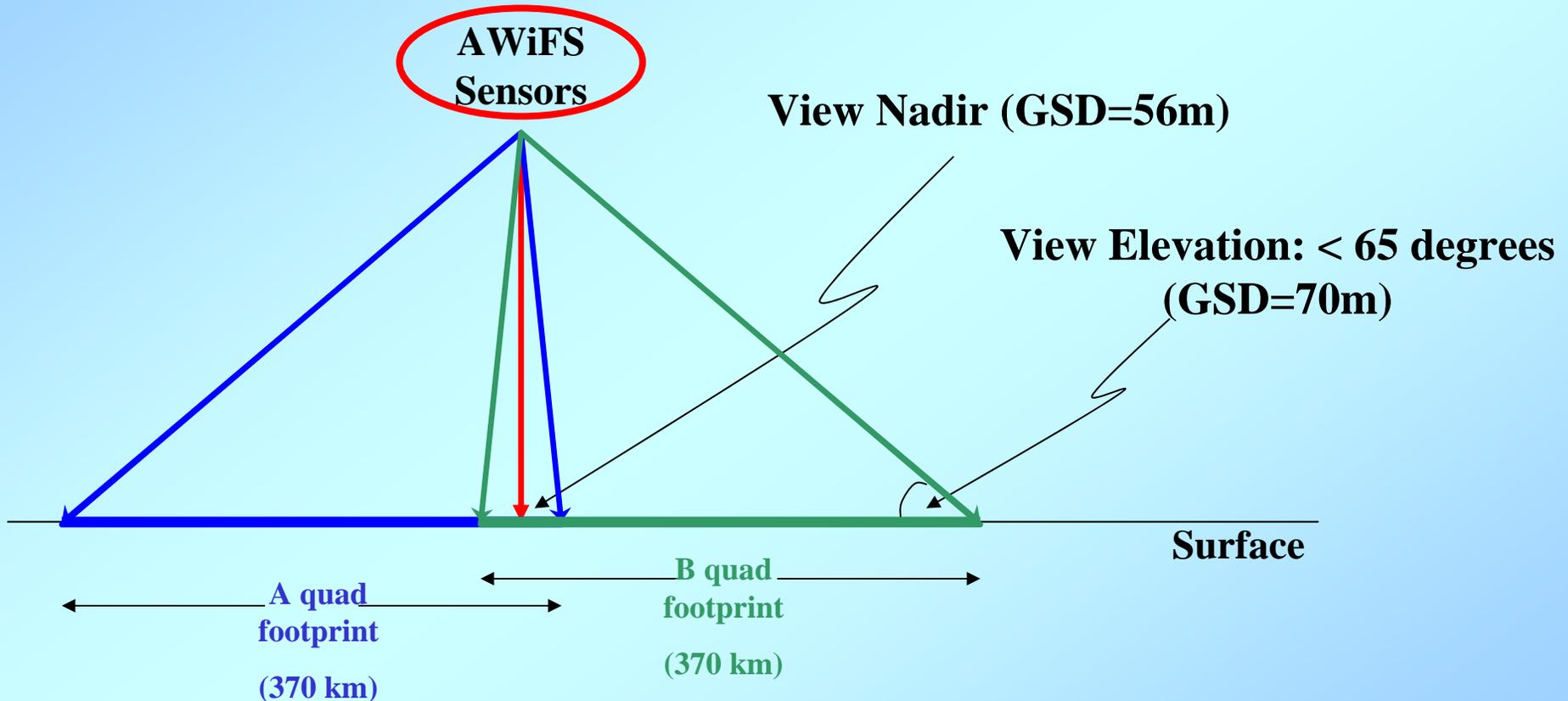
# IRS-P6: AWiFS+Liss3+Liss4

## IRS-P6 THREE TIER IMAGING



# AWiFS Geometry

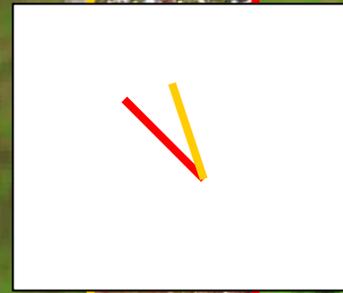
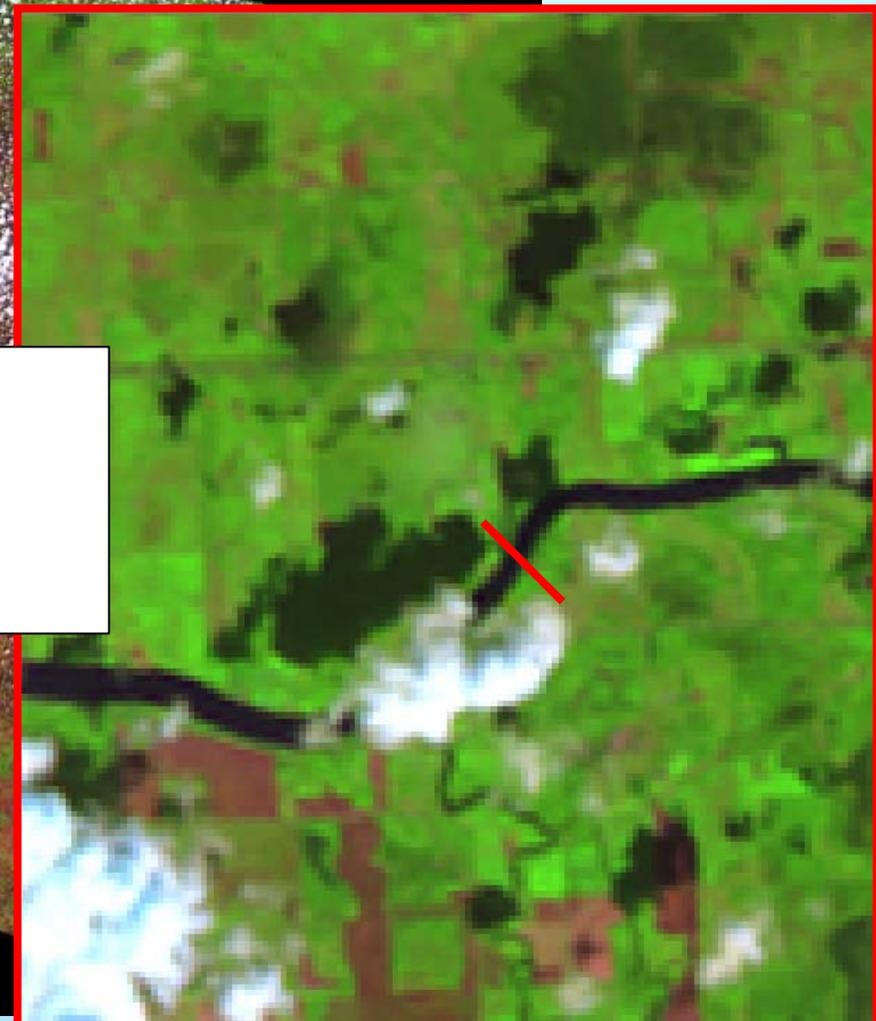
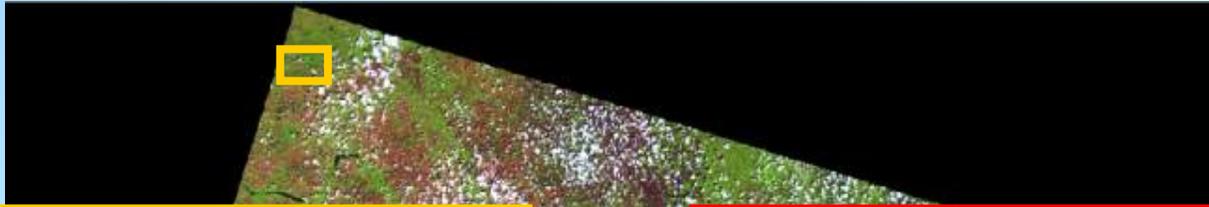
**AWiFS: 11.94 degrees tilt between A & B cameras**



**View Elevation Change from 90 (nadir) to ~65 degrees**



# AWiFS Geometry



# AWiFS Surface Reflectance

Unlike other medium resolution imagery, AWiFS has (among other things):

- Significant variation of view elevation angles across the scene, and hence
- Per pixel differences in atmospheric transmittance along the view path.

GDA Surface Reflectance Calibration:

- Corrects for variations in view geometry & atmospheric transmittance across the scene.
- Calculates surface reflectance values, assuming (i) standard atmosphere and (ii) no surface LC and relief anisotropy, *i.e.*, no BDRF effects and, currently, flat terrain.
- SRS – Surface Reflectance for Standard Atmosphere
- A general equation is below

$$\rho = ( \pi \cdot ( L_{\lambda} - L_p ) \cdot d^2 ) / ( \cos(\Theta) \cdot E_0 \cdot T_z + E_d ) \cdot T_v$$

$\rho$  is surface reflectance,

$L_{\lambda}$  is at-sensor spectral radiance,

$L_p$  is path radiance,

$d$  is earth-sun distance in astronomical units, varies according to the Julian day,

$\Theta$  is sun elevation,

$E_0$  is mean per band solar spectral irradiance value,

$E_d$  is diffuse sky irradiance,

$T_z$  is atmospheric transmittance along the solar path,

$T_v$  is atmospheric transmittance along the view path.

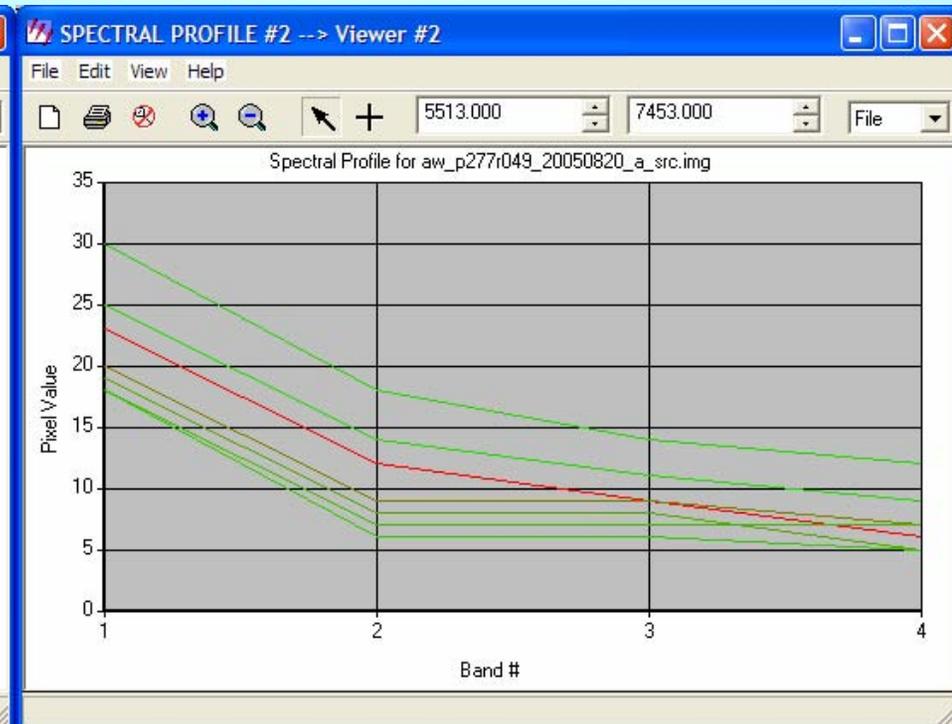
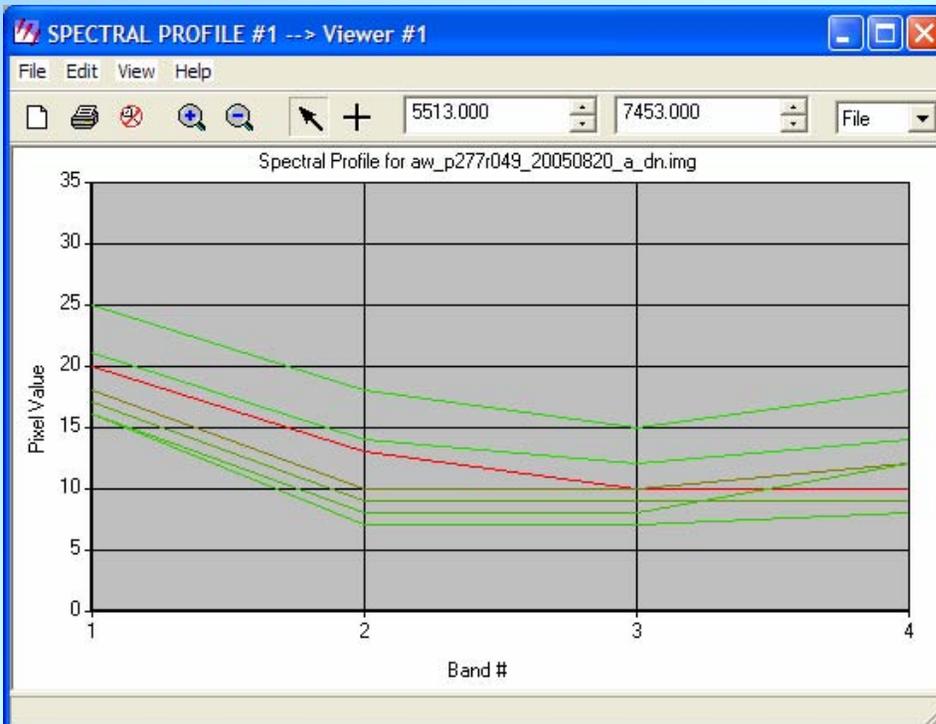


# AWiFS Surface Reflectance

## Water Spectral Properties

DN values

SRS values

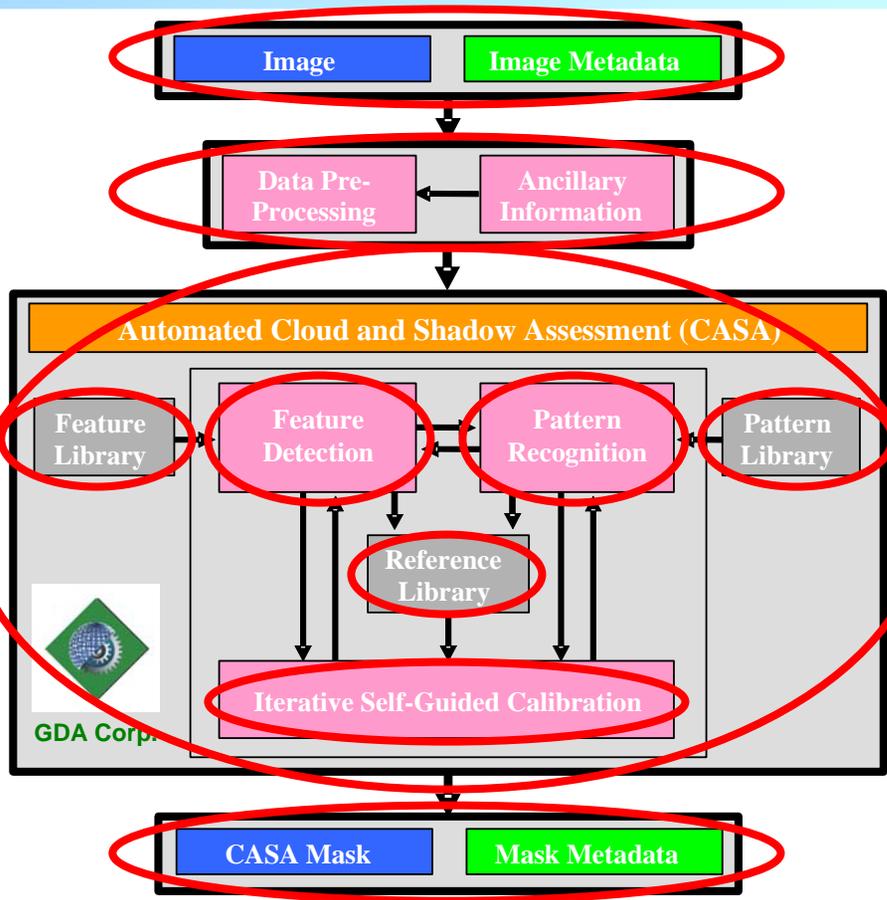


- The same water locations were sampled across DN and SRS imagery



# CASA: Cloud And cloud Shadow Assessment

CASA is a hierarchical self-learning expert system for the automated extraction of a predefined class of features.



## Iterative Evidence / Knowledge Accumulation

- From Global to Scene Specific Knowledge Database
- Spectral
- Spatial
- Contextual / Pattern / Association
- Ancillary Data

## Probability Based

- per Pixel
- per Object

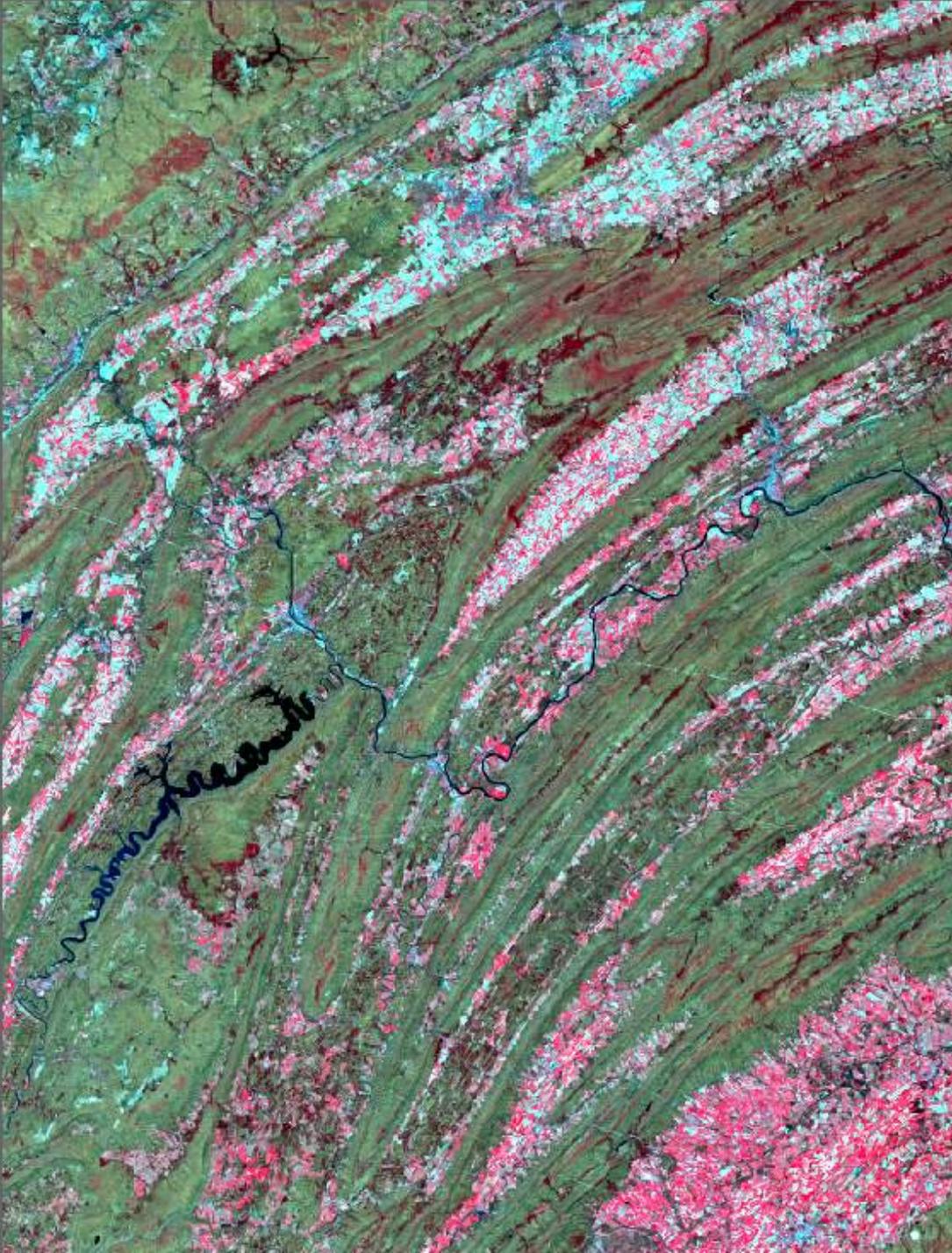
## Flexible

- Can be set to be more or less “aggressive”
- Can work in an interactive mode



# CASA-AWiFS

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## Image Pre-Processing:

- **Surface Reflectance (SRS) Calibration**
- **Confusion Suppression, including**
  - **Topographic Normalization**
  - **Water Detection**
  - **Snow and Ice Detection**

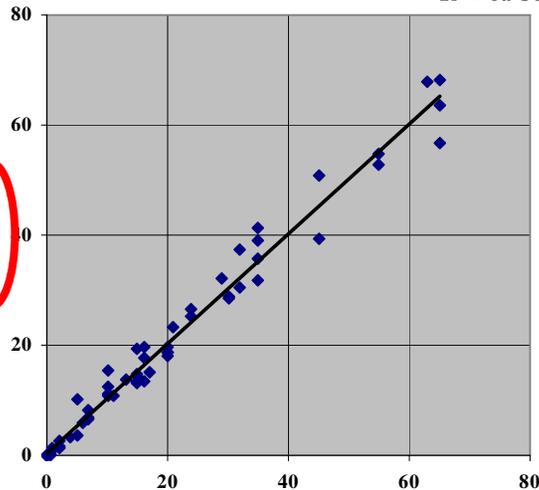


# CASA-AWiFS

## Accuracy of Cloud Detection: CASA vs. Truth Dataset

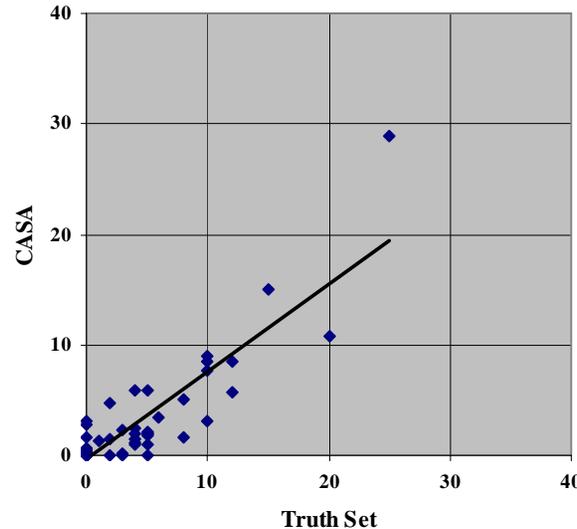
Dense Cloud Cover

$R^2 = 0.9804$



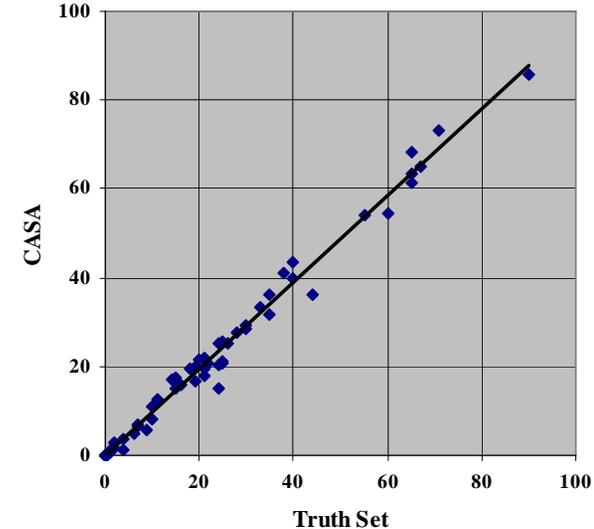
Light CC / Haze

$R^2 = 0.7796$



Total Cloud Cover

$R^2 = 0.988$



### Correlation Values:

Dense clouds: 99.0%

Light, transparent clouds and haze: 88.3%

Combined, clouds and haze: 99.4%



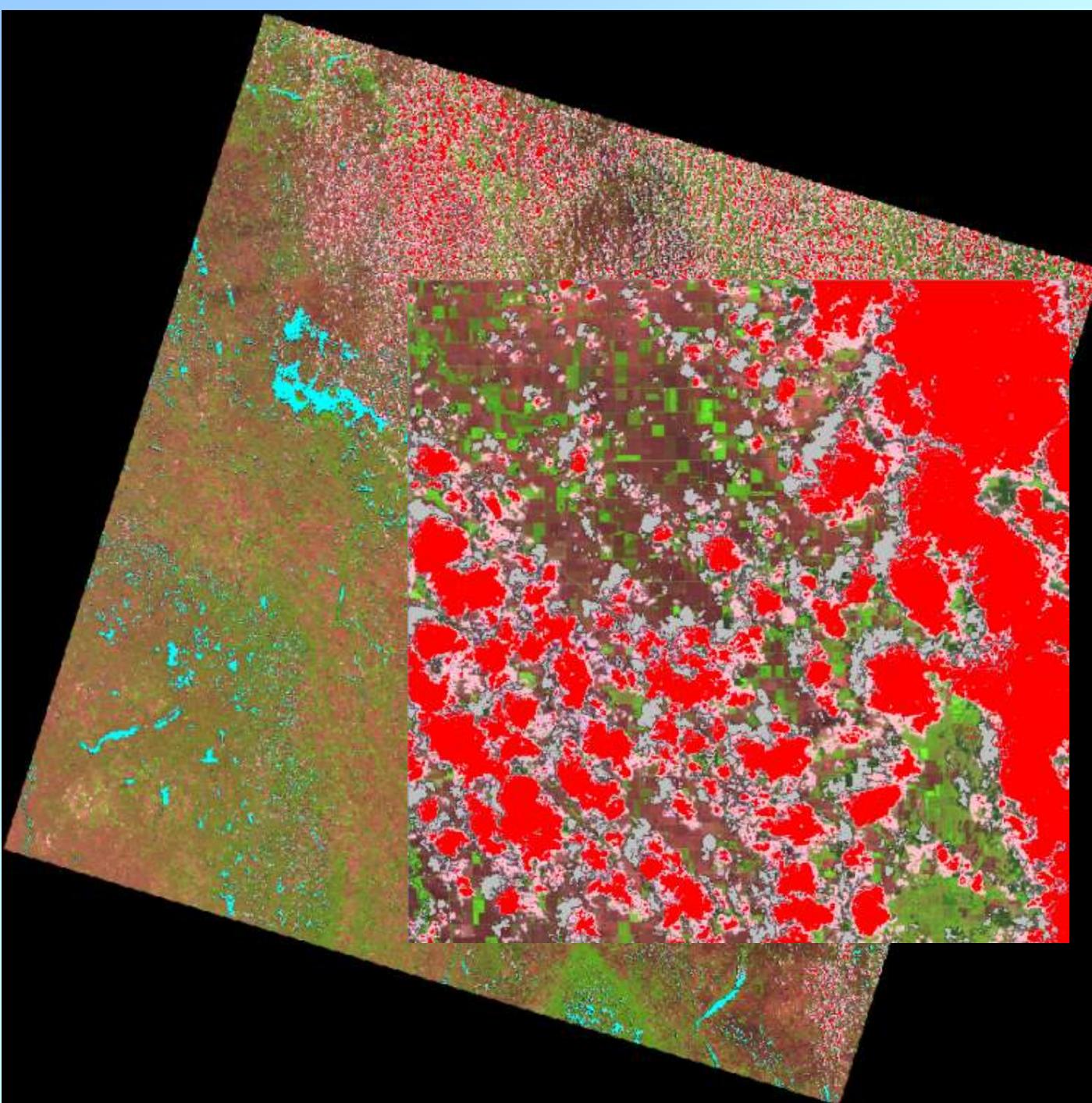
# CASA-AWiFS

## CASA vs. Truth Dataset: Differences in cloud cover estimates by level of error

CASA Error Level	Percent of Scenes		
	Dense Cloud Cover	Light Cloud / Haze Cover	Total Cloud / Haze Cover
0 to 1%	46%	52%	48%
0 to 2%	70%	63%	70%
0 to 5%	89%	94%	95%
0 to 10%	100%	100%	100%
Max Error	8%	9%	9%

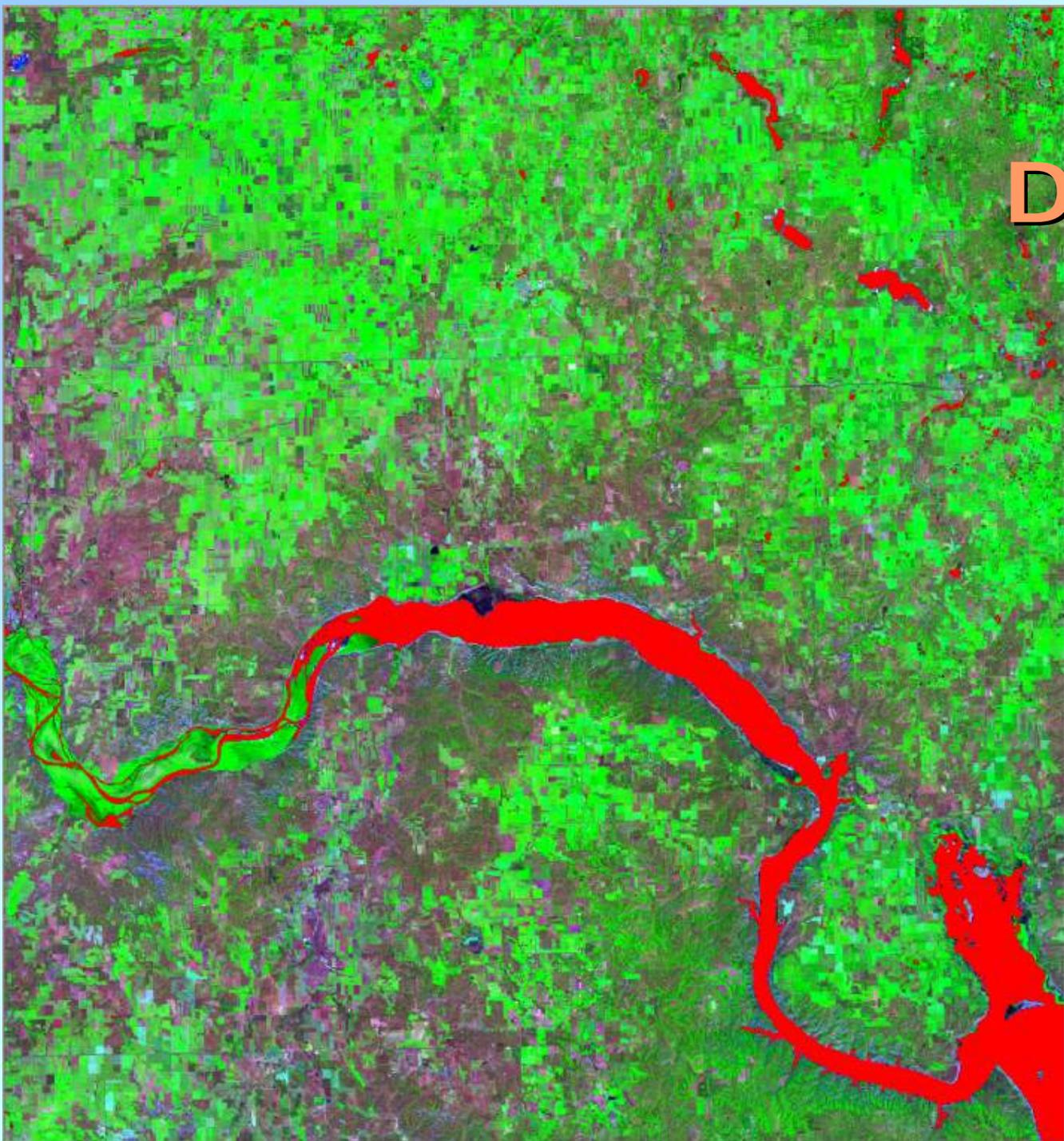


# CASA- AWiFS



-  dense cloud
-  light cloud / haze
-  cloud shadow
-  water



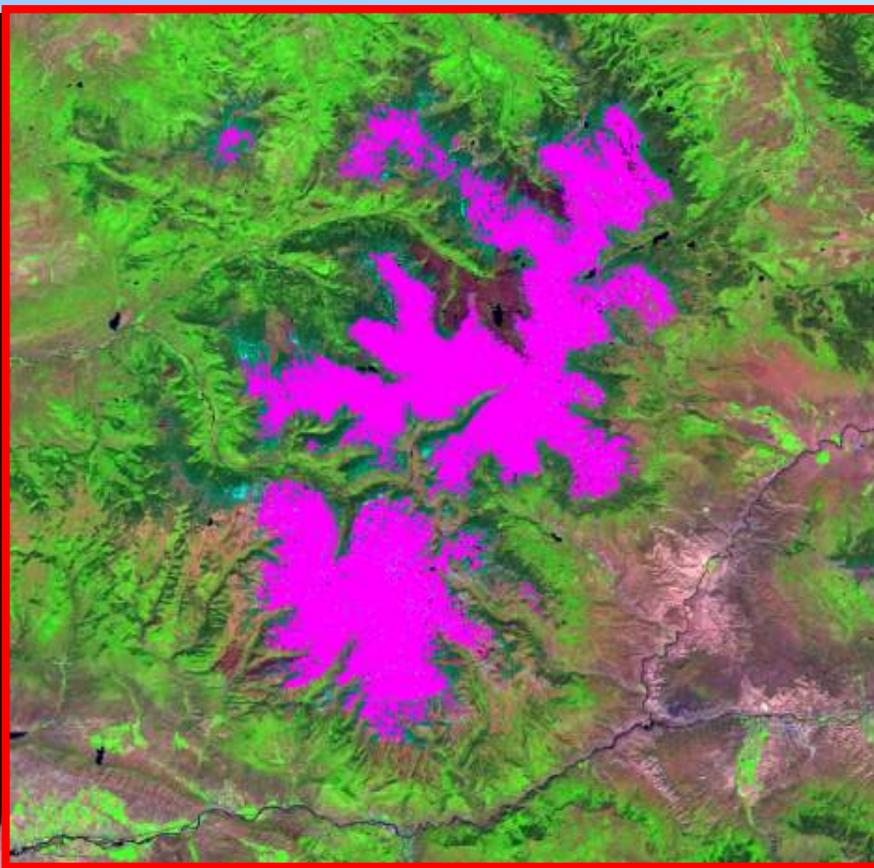
An aerial satellite image of a river system. The water bodies are highlighted in red, while the surrounding land is shown in various shades of green and brown. The river flows from the top left towards the bottom right, with several smaller tributaries branching off.

# Feature Detection: Water

- Self-learning expert system
- Relies on a global knowledge base about water properties and extends global knowledge to the properties of a given scene
- If available, uses ancillary LC information as an extra line of evidence in the decision making process



# Feature Detection: Snow/Ice



The same approach  
is used as for water  
and cloud / cloud  
shadow detection



# Future R&D Plans

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- **Develop CASA-Liss3 version.**
- **Introduce terrain anisotropy into surface reflectance calibration.**
- **Extend feature detection technology to other features such as roads, agricultural fields, buildings, airports, individual trees, *etc.***
- **Complete an automated image classifier for 7 class mapping, including water, transportation, built-up/urban, ground/non-woody vegetation, woody vegetation, snow/ice, and other barren.**



# Acknowledgements

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- **CASA-AWiFS R&D was supported by a NASA Dual Use grant, and advice on this and other CASA projects from NASA COTR, Tom Stanley.**
- **AWiFS imagery has been supplied by the USDA SIA with the help of Bob Tetrault, SIA Manager.**
- **Technical details on AWiFS radiometry and geometry were provided by James Lutes, GeoEye.**



# Additional CASA Info

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<http://www.gdacorp.com/projects/CASA.html>

See bottom of the page for CASA-AWiFS white paper

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