



Overview of Image Quality Performance of the GeoEye-1 High Resolution Imaging Satellite

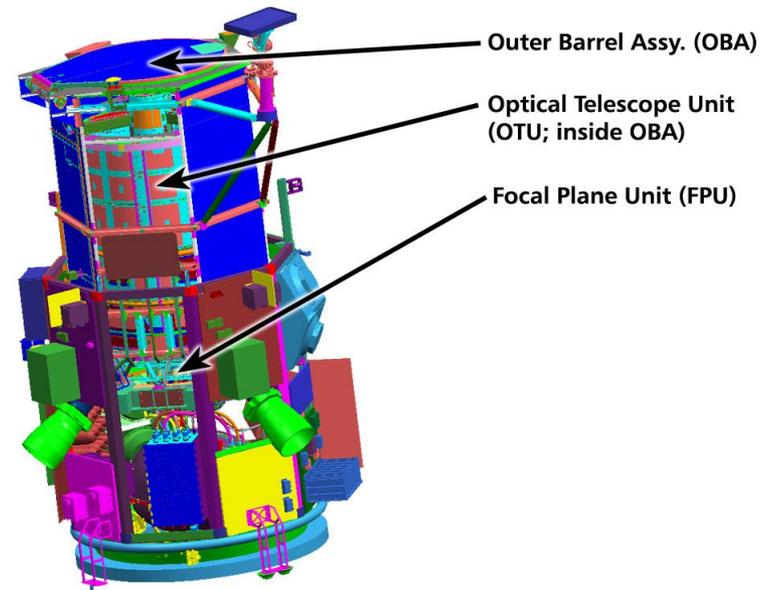
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GeoEye

JACIE, April 18, 2012

Overview

- › Overview of Major Calibrations
- › Overview of Image Quality Assessments Performed
- › Relative Radiometric Calibration Methodology
- › Focus Calibration Methodology



Overview of Major Calibrations for the GE-1 sensor

› Geometric

- Geometric calibration provides the mapping of the satellite sensor for geopositioning imagery.

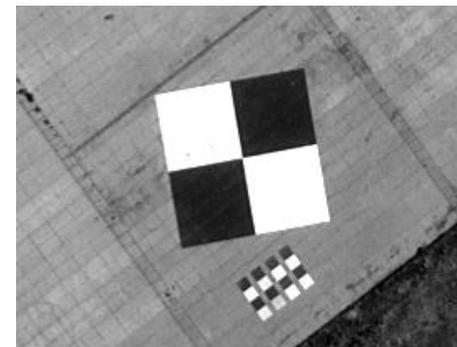
› Radiometric

- Relative radiometric calibration is a detector equalization process to reduce pixel-to-pixel and sub-array to sub-array variations.
- Absolute radiometric is the mapping between digital pixel values and at aperture spectral radiance.

› Focus

- Focus calibration is the process of determining the best focus position of the secondary mirror of telescope.

Overview of Major Image Quality Assessments



MTF Range – Spring, TX

› MTF Analysis -

- MTF is a metric to quantify the sharpness.
- GeoEye maintains a MTF Range - Assessed quarterly
- 1Q12 Camera Level
 - Assessment of spacecraft/payload performance
 - » relative radiometric tables only
 - » No synthetic array interpolation
 - Pan 10K – MTF value 0.14 +/- 0.01, Nyquist MTF of spec 0.1
- 1Q12 Product Level
 - Measured at the earliest customer product level
 - » MTFC kernel applied at the cost of noise
 - Pan 10K – MTF value 0.16 +/- 0.01, Nyquist MTF of spec 0.1

› Signal-to-Noise Measurements

- Measurements are analyzed using flat field imagery
- All bands are within spec

Overview of Major Image Quality Assessments (cont.)

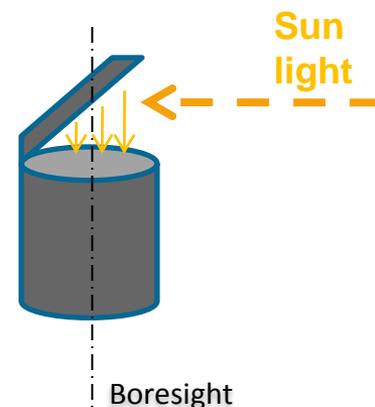
› Time Delay Integration (TDI) Selection Optimization

- TDI selection controls detector exposure time (charged integration time)
- TDI stages for GE-1
 - Panchromatic - 8,16,32,48,64
 - Multispectral - 3, 6, 10, 14, 18, 21, 24
- Optimum selection of TDI is needed to consistently obtain wide dynamic ranges without saturation when imaging.

› Visual assessment of operational imagery for artifact/anomaly characterization and resolution.

Relative Radiometric Calibration

- › **Purpose: Detector equalization to reduce pixel to pixel and sub-array to sub-array (tap) variations.**
- › **Relative calibration data is performed analyzing flat field data collected in for numerous modes (band, aggregation, line speed, TDI).**
- › **Flat field data is acquired by imaging the camera door.**
 - Camera door was coated with a highly reflective paint to produce a diffuse surface.
 - Door opens or closes to allow illumination through the dynamic range of sensor.
 - The sensor must be positioned so that the sun's rays are normal to the both the camera's boresight axis and the camera door hinge.
 - The radiance increases until door has opened to approximately 45 degrees.
 - The door is also imaged while close to obtain dark current data



Relative Radiometric Calibration Methodology

› Dark current value per detector

- Calculated from data acquired when the camera door is closed.
- An average value from approx. 100 scan lines is calculated for each detector.

› Gain correction

- Seven illumination (light) level responses are calculated from the door data for each detector
 - average of approximately 100 lines.
- The dark current value is subtracted from each light levels for each detector.
- Target responses for each light level is determined by the mean value of the 500 middle detector values.
- The target responses and the light levels for each detector make up a lookup table
 - Piecewise linear interpolation during image reconstruction for any digital pixel value

Relative Radiometric Calibration Data – Corrected

MS3, Reverse, 1x1, 6 TDI

The image shows a screenshot of a software window with a blue title bar. The title bar contains the text "#1 Scroll (0.08548)" on the left and standard window control buttons (minimize, maximize, close) on the right. The main content area of the window is a grid consisting of 12 vertical columns. The columns are currently empty, suggesting that the data for this calibration has not yet been loaded or is being prepared. The grid is set against a black background.

Verification of Relative Radiometric Calibration

› Metrics to assess calibration

- Streaking - measure of pixel-to-pixel variation
- Banding - measure of sub-array to sub-array variation

› Verification of Calibrated Camera Door Data

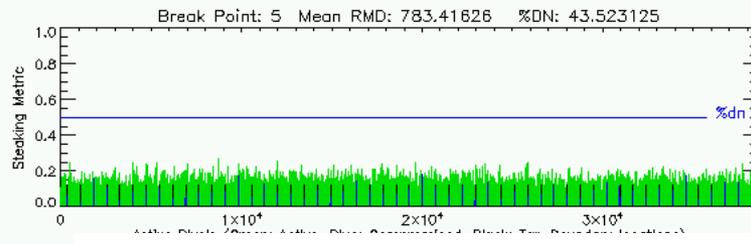
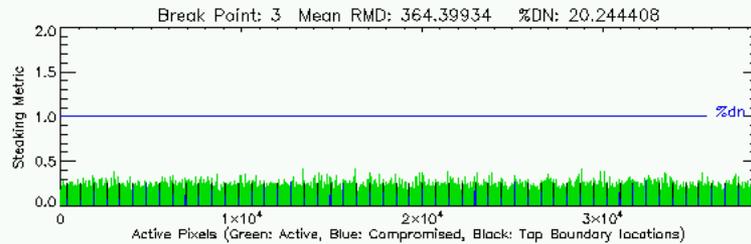
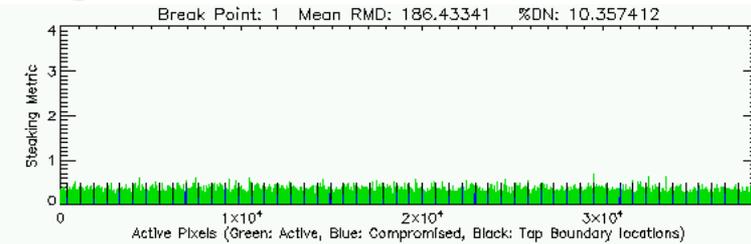
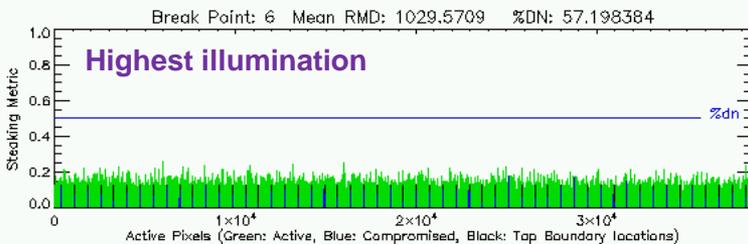
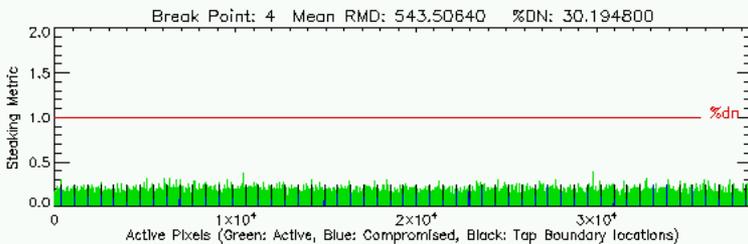
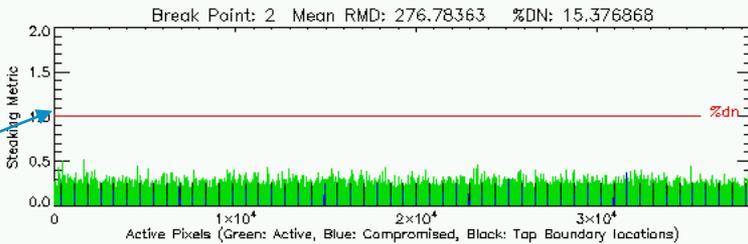
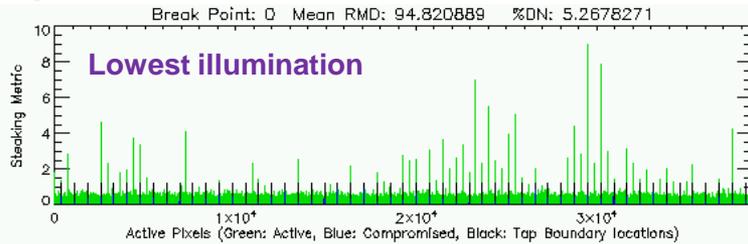
- Streaking and banding metrics are measured across the focal plane and throughout the dynamic range.

› Verification of Operational Image

- Visual inspection
- Banding metrics are measured in homogeneous areas of adjacent sub-arrays.

Representative Streaking Metrics

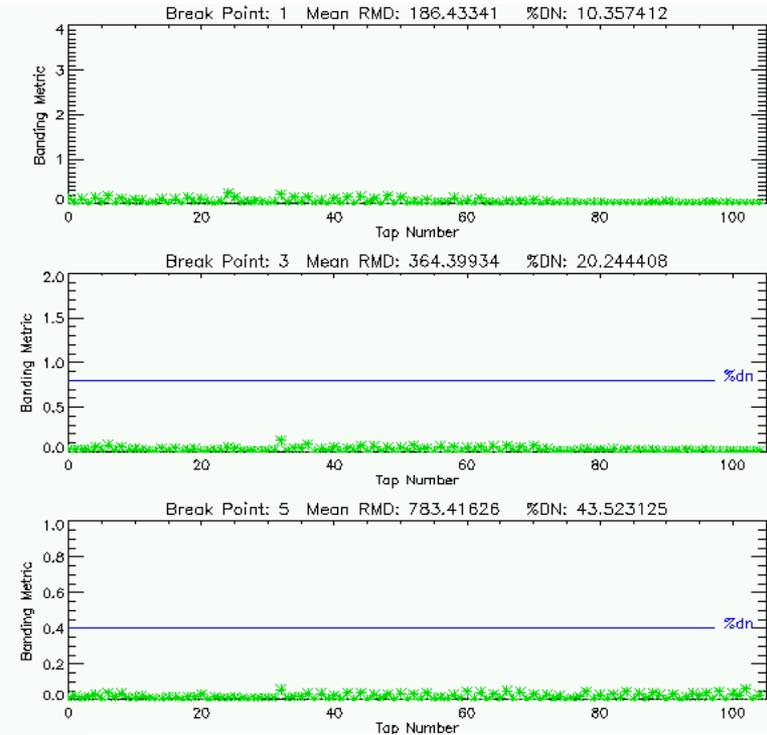
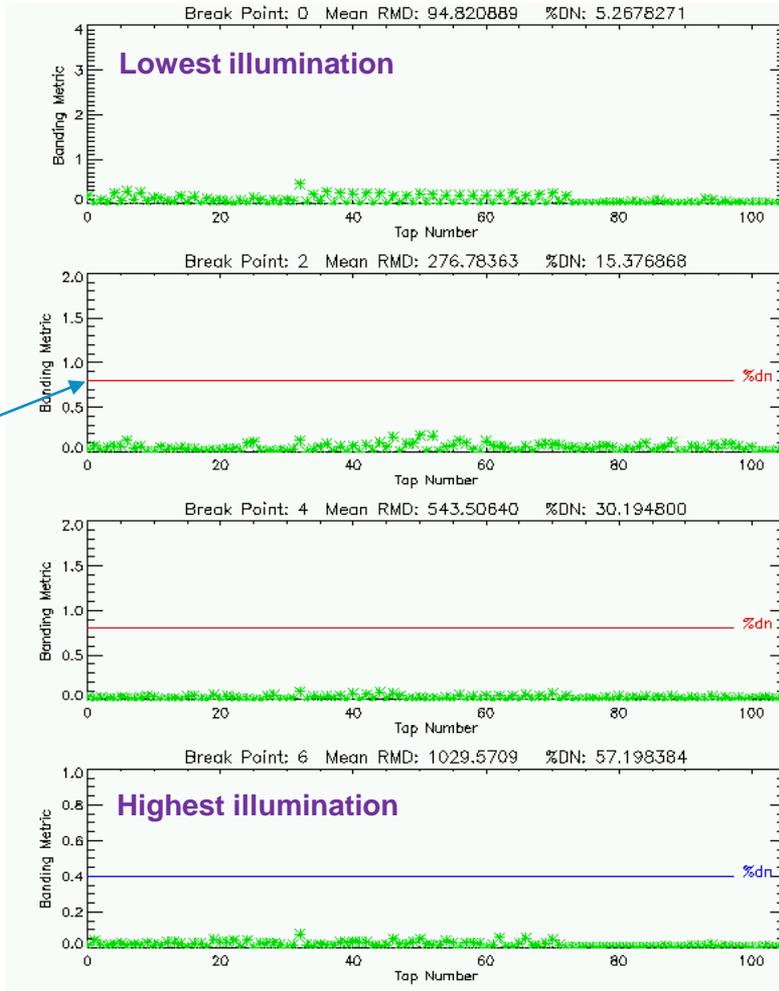
Spec/Requirement



Panchromatic 20,000 Ips
 1x1 Aggregation
 32 TDI
 Reverse Scan

Representative Banding Metrics

Spec/Requirement

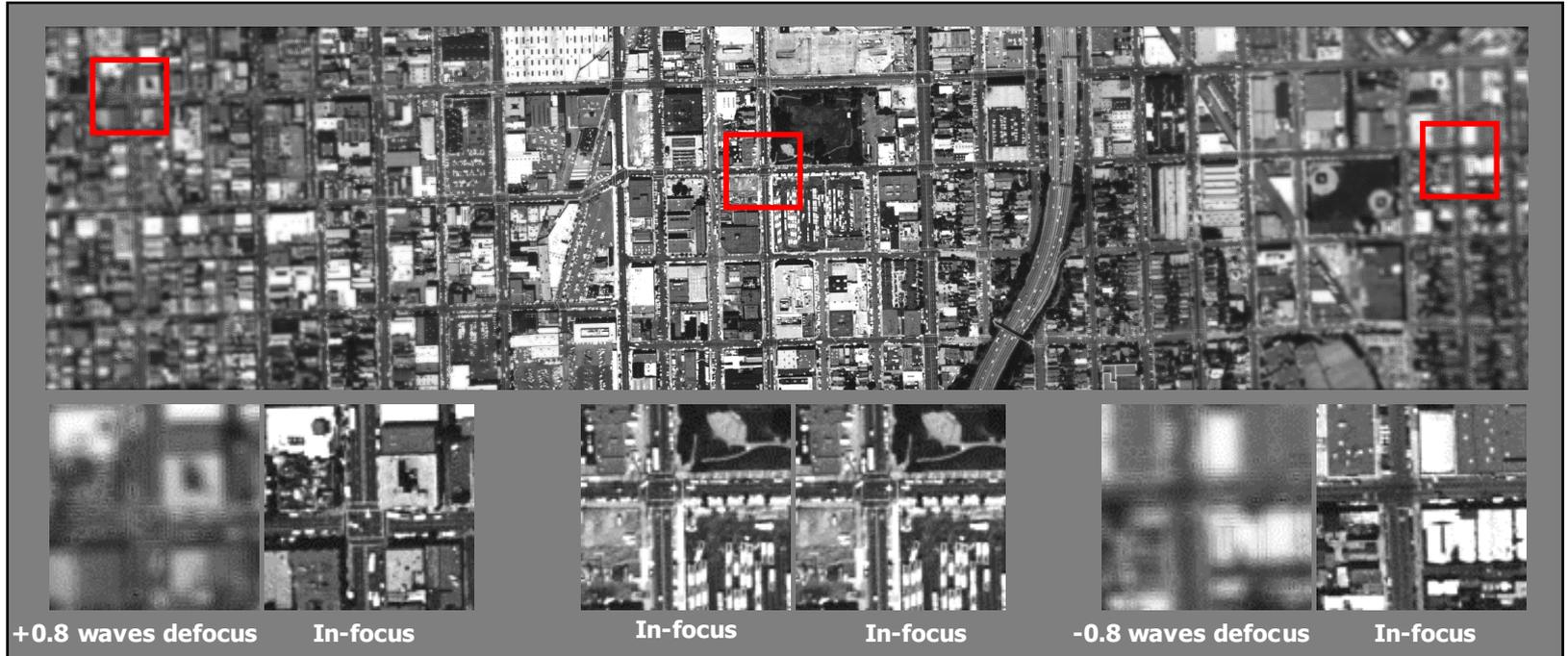


Panchromatic 20,000 Ips
 1x1 Aggregation
 32 TDI
 Reverse Scan

Focus Calibration

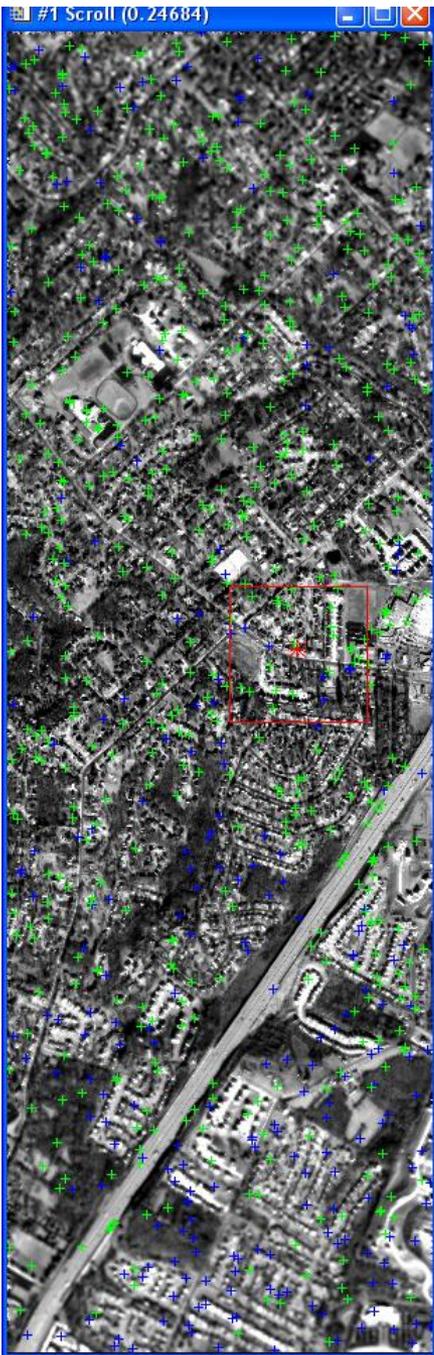
- › **Focus calibration is performed to determine the best focus position of the secondary mirror of telescope.**
- › **Methodology for Obtaining Best Focus**
 - Acquire a “through-focus” image by continuously changing focus during a scan by slewing secondary mirror.
 - Measure image sharpness by a digital edge detector throughout the “through-focus” image.
 - A polynomial curve is fitted to the edge detector metrics and the maximum determines the optimum focus (secondary mirror position).

Focus Calibration – “Through-focus” scan

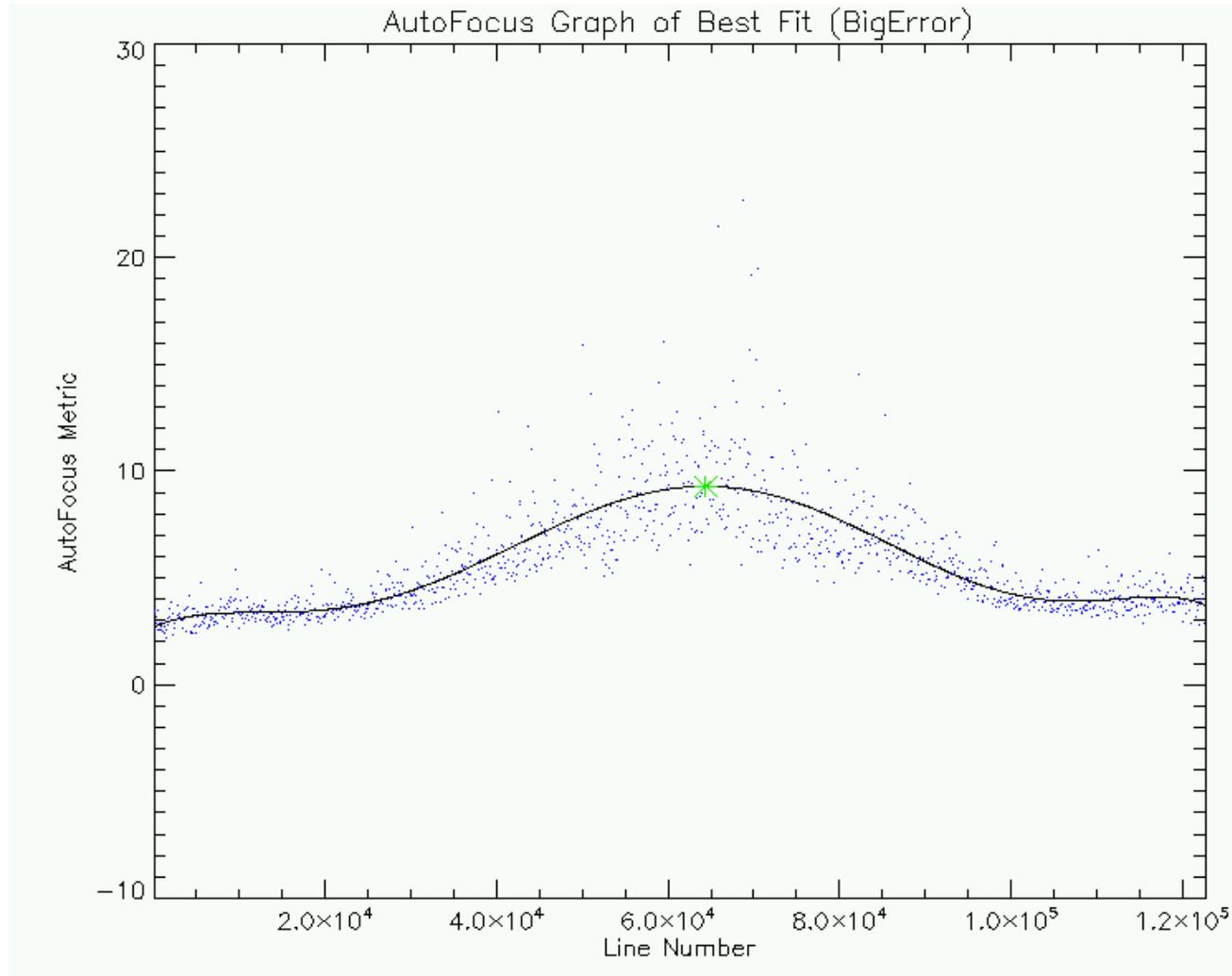


-120 steps

+120 steps



Automatic focus determination.



Summary

- › **The GE-1 system continues to provide high quality imagery**
- › **GE-1 remains in specification**
 - Radiometric
 - Geometric
 - MTF
 - SNR
- › **Scans are continuously monitored to maintain high image quality.**

Questions?



Great Sphinx of Giza, Egypt

Absolute Radiometric Calibration

- › **Purpose: Determination of calibration coefficients to convert digital numbers (DN) to spectral radiance (mW/(cm²*str*μm)).**

$$L_{band} = Coef_{band} * DN_{band} + Offset_{band} \quad (\text{Note: offset} = 0.)$$

- Coefficients vary according to camera setting.
 - Line rate, TDI, scan direction.
- Coefficients contained in metadata delivered with image products.
- › **Current coefficients are based on pre-launch measurements.**
 - Uncertainty ≤ 10% across 5-19% of saturation levels.
 - Uncertainty ≤ 5% across 20-90% of saturation levels.
- › **On-orbit verification of absolute radiometric coefficients are performed by**
 - Analyzing responses from measuring radiometric stars – analysis underway
 - Measuring terrestrial target – analysis underway