



# ALASKA STATEWIDE DIGITAL MAPPING INITIATIVE

Exploring Medium and High Resolution Commercial Imagery  
Solutions to Meet Statewide Mapping Needs in Alaska

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i-cubed



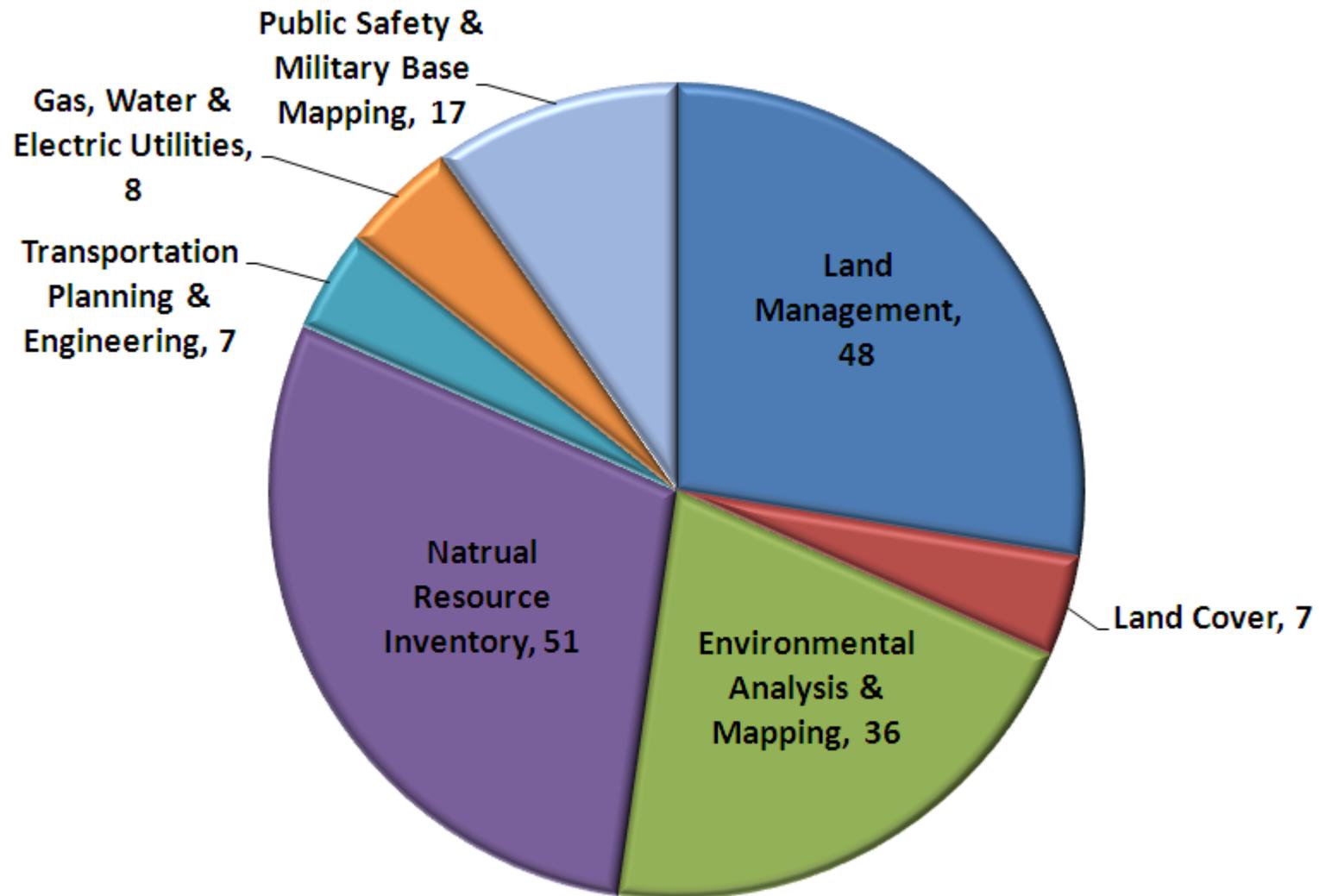
## GOALS OF SDMI

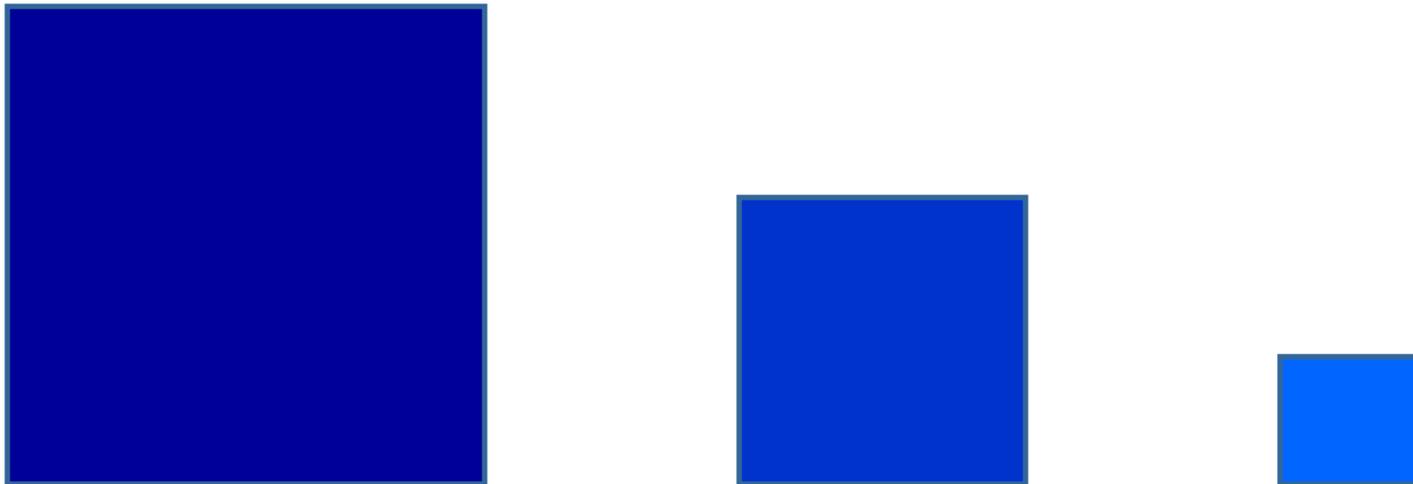
- **CREATE A BASE MAP OF ALASKA:** Acquire imagery and digital elevation data necessary to meet specifications, generate ortho-imagery and DEMs, and assess accuracy of final products.
- **CREATE THE ARCHIVE:** Develop the project infrastructure to warehouse, archive and make products available to the public.
- **LIFECYCLE MANAGEMENT OF THE BASE MAP DATA:** Provide ongoing management of the base map data.

## DEM COMPONENT

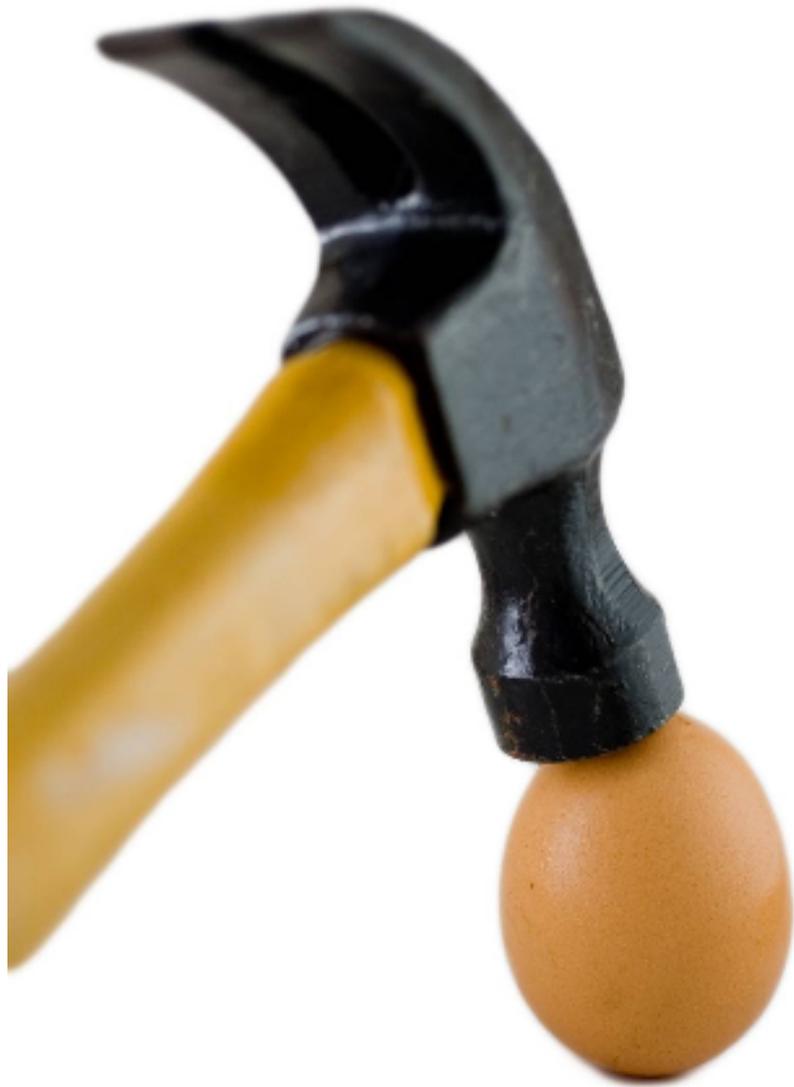
- Separate workshop and whitepaper
- [www.alaskamapped.org](http://www.alaskamapped.org)
- DTED-2 for 1:24k NMAS image map
- Project based lidar
- IFSAR for Aviation Safety, detailed hydrology, costal erosion etc.
- Dave Maune from Dewberry is under contract to build state and federal consensus and get funding







# Variable Resolution Needs



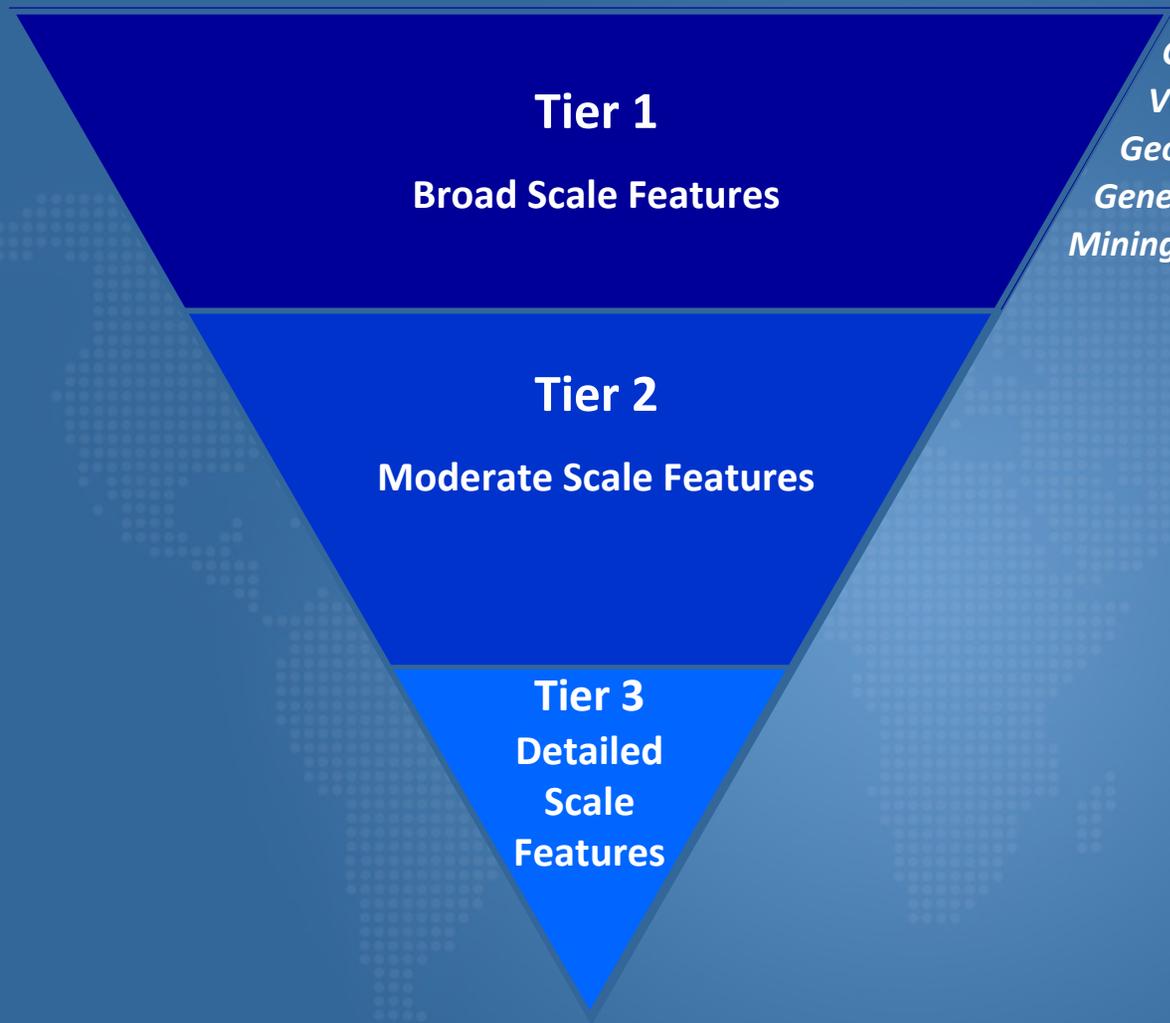
## Beware of Overkill



**Tier 1**  
**Broad Scale Features**

**Tier 2**  
**Moderate Scale Features**

**Tier 3**  
**Detailed Scale Features**



*Climate Change*  
*General Hydrographic Features*  
*Vegetation Land cover*  
*Geologic Unit Mapping*  
*General Wetlands Mappings*  
*Mining*

**Tier 1**  
**Broad Scale Features**

- Climate Change*
- General Hydrographic Features*
- Vegetation Land cover*
- Geologic Unit Mapping*
- General Wetlands Mappings*
- Mining*
- Underlay for Parcel /Property Boundaries*
- Underlay for Land use & Natural Area Boundaries*

**Tier 2**  
**Moderate Scale Features**

- General Urban & Rural Cover*
- Discrete Hydrographic Features (riverbanks/ponds)*
- Extraction of Land use & Natural Area Boundaries*
- Mapping Protected Areas & Trails*
- Agricultural Mapping & Monitoring*
- Tree Canopies*

**Tier 3**  
**Detailed Scale Features**

**Tier 1**  
**Broad Scale Features**

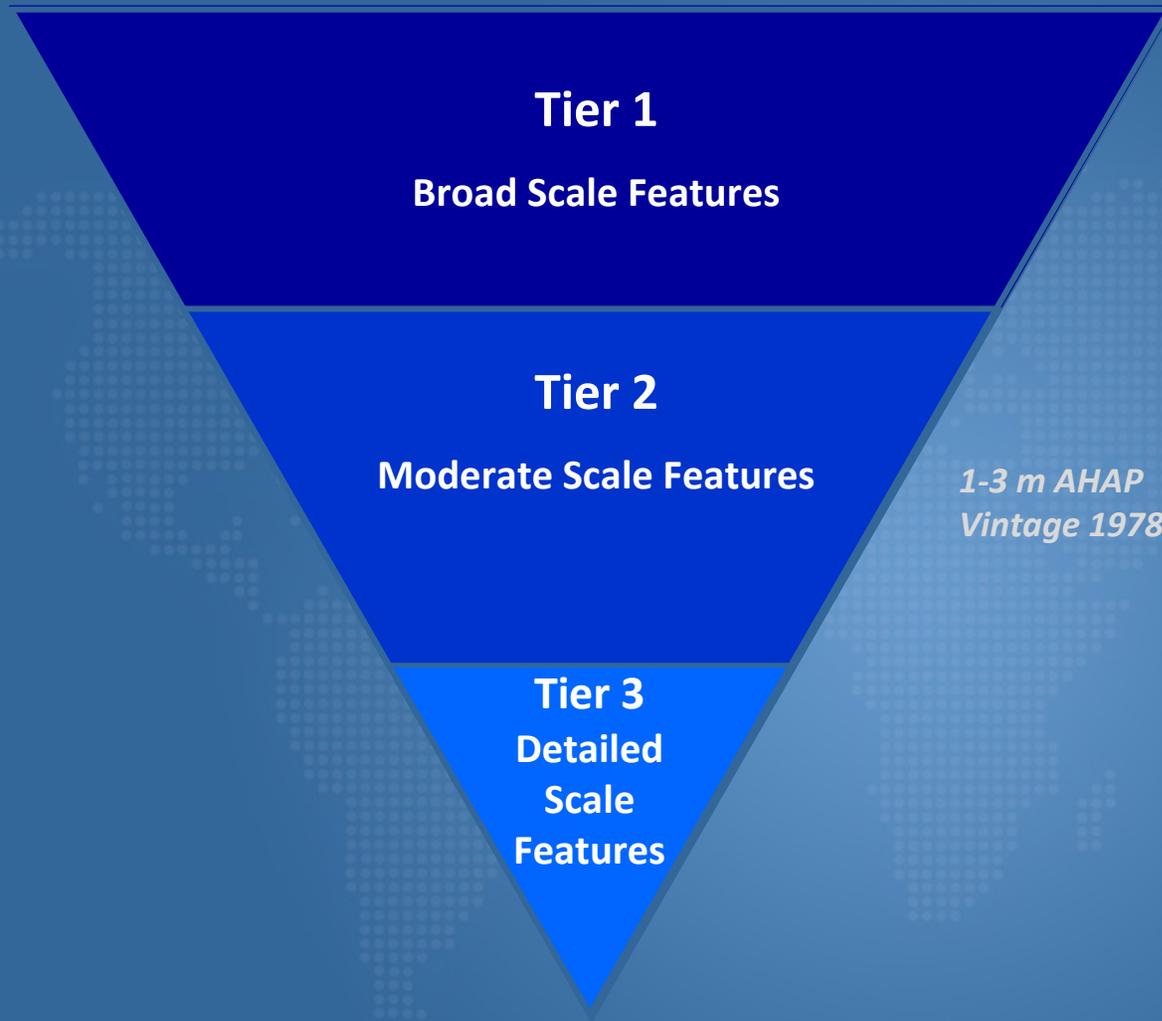
**Tier 2**  
**Moderate Scale Features**

**Tier 3**  
**Detailed Scale Features**

- Climate Change*
- General Hydrographic Features*
- Vegetation Land cover*
- Geologic Unit Mapping*
- General Wetlands Mappings*
- Mining*
- Underlay for Parcel /Property Boundaries*
- Underlay for Land use & Natural Area Boundaries*
- General Urban & Rural Cover*
- Discrete Hydrographic Features (riverbanks/ponds)*
- Extraction of Land use & Natural Area Boundaries*
- Mapping Protected Areas & Trails*
- Agricultural Mapping & Monitoring*
- Tree Canopies*
- Discrete Wetlands Boundaries*
- Extraction of Parcel / Property Boundaries*
- Pipeline Mapping*
- Parking lots & impervious surface*
- Military Base Mapping*
- Major Road Intersections / Road Centerlines*
- Commercial & Household Building Footprints*
- Utilities (hydrants, electric power poles etc.)*



15 – 30 m Landsat



*1-3 m AHAP Alaska High Altitude Aerial Photography  
Vintage 1978 - 1986*



*15 – 30 m Landsat*

*10 m SPOT-5 MS, ALOS AVNIR-2 MS*

*6.5 m RapidEye MS (5 m RapidEye MS Ortho)*

*5.8 m LISS-4 MS*

*5 m SPOT PAN/PSM*

*4 m IKONOS MS*

*2.8 m QuickBird MS*

*2.5 m SPOT PAN/PSM, ALOS PRISM PAN*

*1-3 m AHAP Alaska High Altitude Aerial Photography  
Vintage 1978 - 1986*

## Tier 1

Broad Scale Features

## Tier 2

Moderate Scale Features

Tier 3  
Detailed  
Scale  
Features



15 – 30 m Landsat

10 m SPOT-5 MS, ALOS AVNIR-2 MS

6.5 m RapidEye MS (5 m RapidEye MS Ortho)

5.8 m LISS-4 MS

5 m SPOT PAN/PSM

4 m IKONOS MS

2.8 m QuickBird MS

2.5 m SPOT PAN/PSM, ALOS PRISM PAN

1-3 m AHAP Alaska High Altitude Aerial Photography  
Vintage 1978 - 1986

1.65 m GeoEye-1 MS

1 m IKONOS PAN/PSM

0.6 m QuickBird PAN/PSM

0.5 m WorldView-1 PAN

0.5 m GeoEye-1 PAN/PSM

Aerial Orthophotography

## Tier 1

Broad Scale Features

## Tier 2

Moderate Scale Features

Tier 3  
Detailed  
Scale  
Features



% of respondents requiring color, MS, or CIR imagery is **77%**

# Refresh of Imagery every



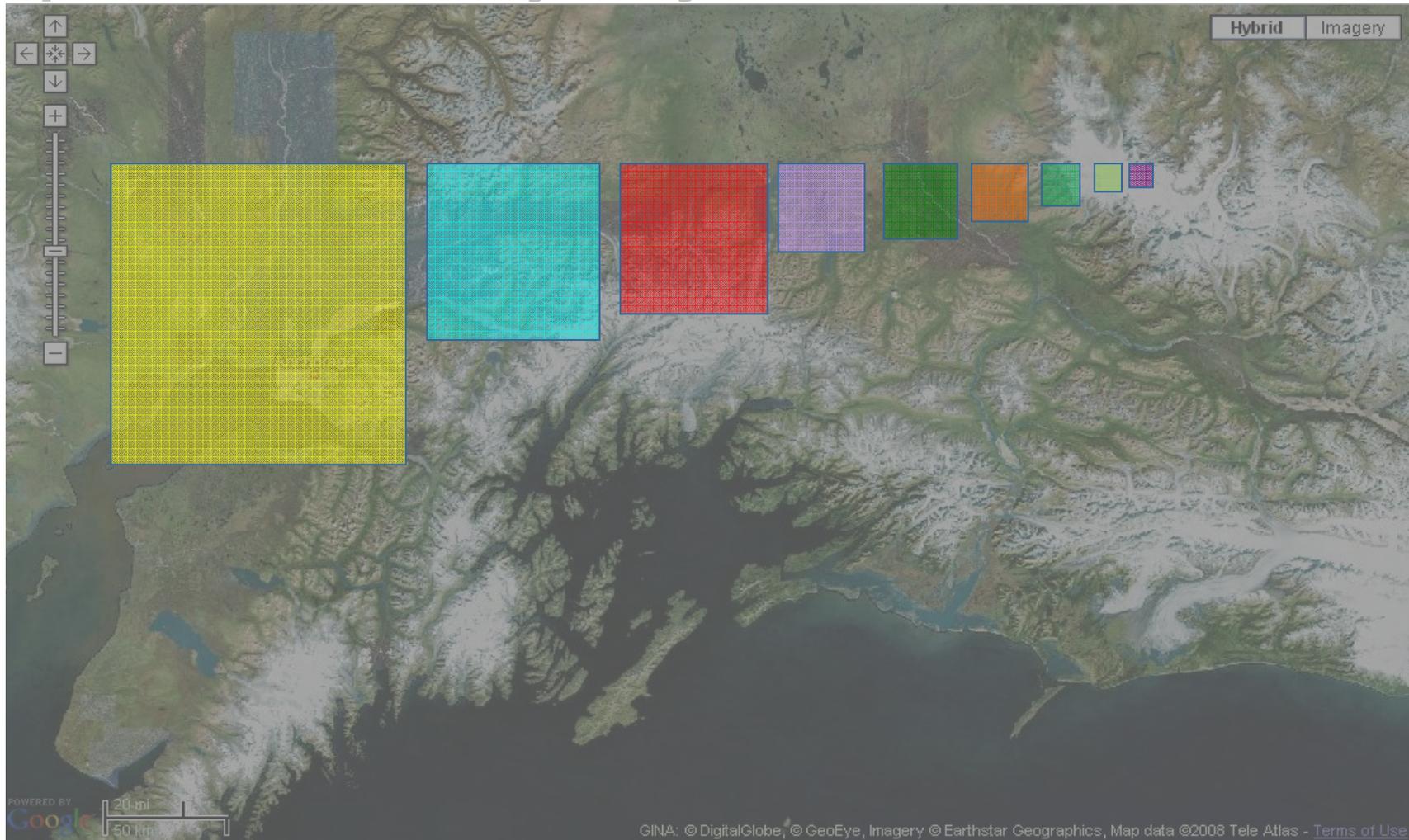
**70% want minimum 5 year refresh of imagery basemap**  
**46% favor 3 year refresh or better**

# MAPPING ALASKA

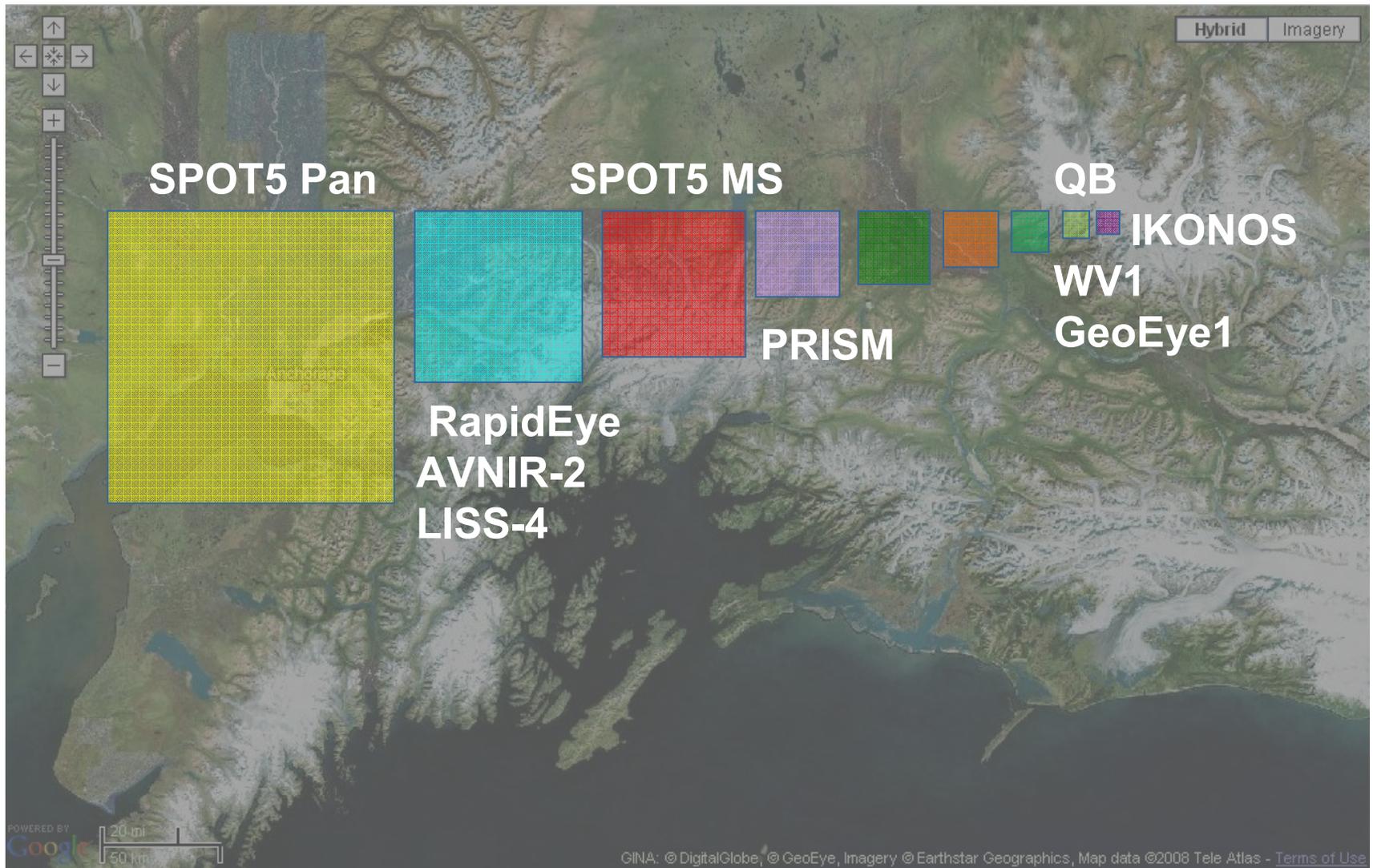


IMAGE COURTESY OF AEROMETRIC

# Collection Capacity & Spectral Continuity Vary w/ Sensor



# Some Examples





# MAPPING SCALES

1:63,360

**Tier 1**

**Broad Scale Features**

1:24,000

**Tier 2**

**Moderate Scale Features**

1:12,000

**Tier 3**  
**Detailed**  
**Scale**  
**Features**

1:2,400



## 2 MEANINGS OF MAPPING SCALE

- Accuracy
  - Often to NMAP or CE90 etc.
  - Fairly easy to plan and measure
  - DEM component is often misunderstood caveat for policy makers
- Display
  - Feature identification
  - Correlation with traditional uses of topographic map scales
  - Scale      Res. (m)
  - 100,000      10.0
  - 50,000      5.0
  - 24,000      2.4
  - 12,000      1.2

## ERROR BUDGET

- The term *error budget* (also known as *uncertainty budget*) is used by many industries to mean the partitioning of total error into specific components, in order to evaluate the impact of each on the overall system. Ideally, an error budget is used early in a process to help the designers of a system choose components that minimize or eliminate errors, in order to meet a certain overall accuracy requirement (Mancini).
- In remote sensing, an error budget is used to define and quantify the various sources that contribute to the inaccuracy (also known as circular error) in a given project area. By identifying these specific sources of error, the components that supply the most error or that can be most easily remedied are identified (Congalton).



# ERROR BUDGET CALCULATIONS

	A	B	C	D	E	F	G	H	I	J	K	L
5	This worksheet will calculate the expected accuracy of an orthoimage, or a set of orthoimages											
6												
7	Enter information in blue areas.											
8	Results are shown in red areas.											
9												
10												
11	<b>Project information:</b>											
12												
13	Project Name:				Alaska SDMI							
14	Location:				Alaska							
15	Accuracy level (CE/LE %):				90							
16	What units do you want to use? Enter meters, feet, inches, or centimeters				meters							
17												
18	<b>Satellite information:</b>											
19												
20	Name of satellite:				IKONOS							
21	Source pixel size in meters:				1.00 (m)							
22	Maximum look angle in project area:				24.00 (deg)							
23	Error inherent in satellite model (CE90) with best method (e.g. rigorous) using ground control:				2.000 (m)							
24	Error inherent in satellite model/ephemeris (CE90) with best method (e.g. RPCs) - satellite source dependent:				10.000 (m)							
25												
33	<b>DEM information:</b>											
34												
35	Description of DEM:				G-DEM							
36	Vertical error (LE90):				11.58 (m)							
37	Horizontal error (CE90):				0.00 (m)							
38	90th percentile of slope (can extrapolate from DEM):				0.00 (%)							
39												
40	<b>Orthorectification:</b>											
41												
42	Are you using ground control? Enter Y or N.				y							
43												
44	<i>If using ground control - follow minimum ground control recommendations at right</i>											
45	Circular accuracy (CE90) of ground control:				10.900 (m)							
46	Photo-identifiable precision of ground control (use 0.5 pix if good):				1.000 (input pix)							
47												
48	<b>Predicted circular accuracy of orthorectified product:</b>											
49												
50	Error due to vertical accuracy of DEM:				5.156 (m)							
51	Error due to horizontal accuracy of DEM:				0.000 (m)							
52	Error due to ground control circular error:				10.900 (m)							
53	Error due to ground control photo-identifiability:				1.000 (m)							
54	Error due to satellite model:				2.000 (m)							
55	<b>Predicted circular accuracy (CE90):</b>				<b>12.263 (m)</b>							
56	CE90/NMAS error				12.263 (m)							
57	CE95/NSSDA error				14.613 (m)							
58	NMAS scale				1: 24,141							

Horizontal (circular) error conversion		
input level	90	CE % or RMSE
input error	6.50	(m)
output level	90	CE %
output error	6.50	(m)

Vertical error conversion		
input level	68	LE % or RMSE
input error	7.00	(m)
output level	90	LE %
output error	11.58	(m)

Minimum ground control recommendations	
QuickBird	10x10 km
IKONOS	10x50 km, min. 2 per strip
SPOT	10 points per scene
Others	check with vendor

# Supporting Documentation

1 i-cubed proprietary information

## SATELLITE ORTHO ACCURACY ESTIMATION WORKSHEET

11 i-cubed proprietary information

YUSUF SIDDIQUI, RESEARCH  
I-CUBED : INFORMATION I

### INTRODUCTION

The term *error budget* (also known as total error) is used early in a process to eliminate errors, in order to meet a

In remote sensing, an error budget (also known as circular error probability) is used to estimate the accuracy of a satellite ortho accuracy estimation. Components of an error budget for each field of the spreadsheet, follow the same logic as the calculations.

Note that the words *accuracy* and *precision* are used interchangeably.

### GENERAL SPREADSHEET TIPS

The user should enter information in the spreadsheet. The accuracy level will not be able to overwrite them. In the spreadsheet, the instruction section or another, the instruction

### PROJECT INFORMATION SECTION

This is where basic information about the project is entered. The accuracy level is 63.21%, 90% or 95%. If evaluating for NSSDA, 95% should be used. The last field in this section is for the user to enter the accuracy level asked for or reported.

July 21, 2008

### APPENDIX 1 – SATELLITE ANGLE RELATIONSHIPS

Figure 4 shows the triangular relationship between the satellite, the ellipsoid, and the approximate center of the earth. The angle subtended at the center of the earth is the angular difference between the incidence angle and the look angle, due to the fact that the three angles of the triangle must add up to 180°:

$$\theta_i + \theta_s + (180^\circ - \theta_i) = 180^\circ \quad (\text{Eq. 13})$$

$$\theta_i = \theta_i + \theta_s \quad (\text{Eq. 14})$$

where  $\theta_i$  = look angle  
 $\theta_s$  = angle subtended  
 $\theta_i$  = incidence angle

The Law of Sines can be used to calculate the third angle of the triangle in Figure 4, which in turn can be used to calculate the incidence angle (using the trigonometric identity  $\sin \theta = \sin(180^\circ - \theta)$ ):

$$\frac{r_s + h_s}{\sin \theta_i} = \frac{r_g}{\sin \theta_s} \quad (\text{Eq. 15})$$

$$\theta_i = \sin^{-1} \left( \sin \theta_s \frac{r_s + h_s}{r_g} \right) \quad (\text{Eq. 16})$$

where  $r_s$  = earth radius at satellite  
 $h_s$  = height above ellipsoid of satellite  
 $r_g$  = earth radius at ground

Given an ellipsoid, a latitude, and a longitude, the ellipsoidal radius of the earth at any given point can be calculated. Since we do not necessarily know where the satellite or scene center will be, the earth can be approximated as a sphere to get around the need to have a location. The mean earth radius of 6371 km is used in the spreadsheet. Substituting this in to Equation 16 gives:

$$\theta_i = \sin^{-1} \left( \sin \theta_s \frac{r_m + h_s}{r_m} \right) \quad (\text{Eq. 17})$$

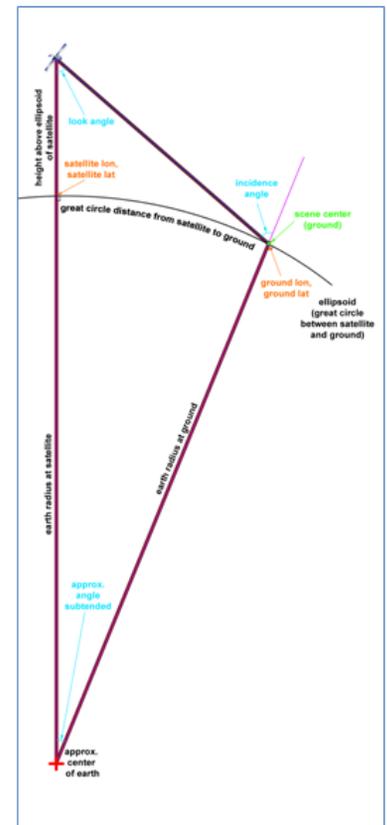


Figure 4



# APPROXIMATE MAP SCALE EQUIVALENCIES

Map Scale	CE90	RMSE	1-Sigma
1:50,000	25.4m	15m	12m
1:24,000	12.2m	6m	3m
1:12,000	10.2m	5m	2m
1:4,800	4.1m	2m	2m
1:2,400	2.0m	1m	1m

# ROOT SUM SQUARE

- Overall error is not a linear additive function of the errors but rather the square root of the sum of the squares of the errors because there is some natural cancellation if one assumes the errors are random.

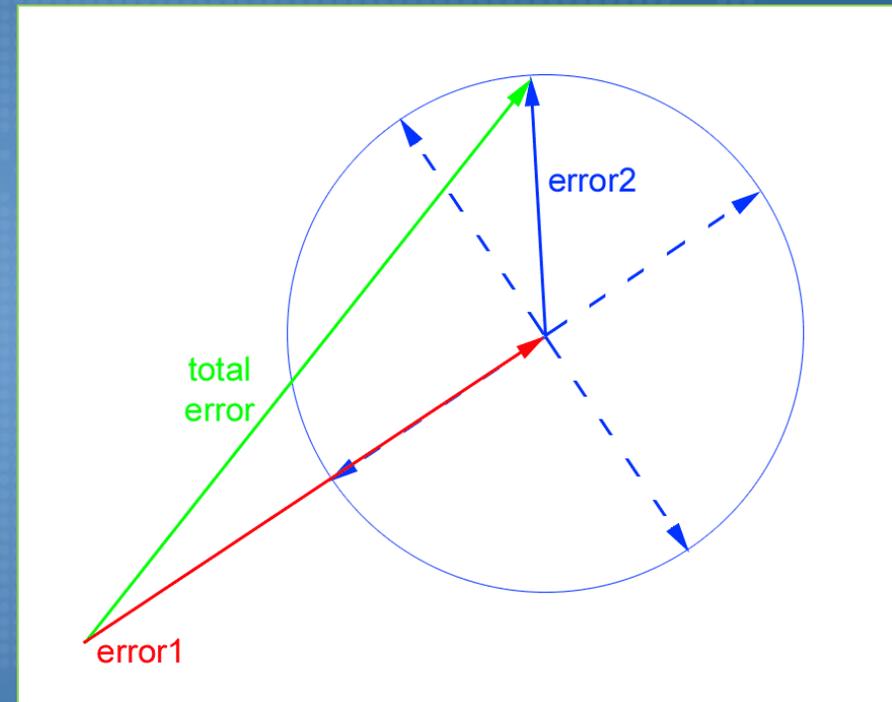
$$\epsilon_p = \sqrt{\sum \epsilon_i^2}$$

Predicted circular accuracy of orthorectified product:			
Error due to vertical accuracy of DEM:	5.156	(m)	
Error due to horizontal accuracy of DEM:	0.000	(m)	
Error due to ground control circular error:	1.000	(m)	
Error due to ground control photo-identifiability:	1.000	(m)	
Error due to satellite model:	2.000	(m)	
<b>Predicted circular accuracy (CE95):</b>	<b>5.708</b>	<b>(m)</b>	<b>9.156</b>
CE90/NMAS error	4.790	(m)	
CE95/NSSDA error	5.708	(m)	
NMAS scale 1:	6,742		

rss → (points to 5.708)  
linear → (points to 9.156)

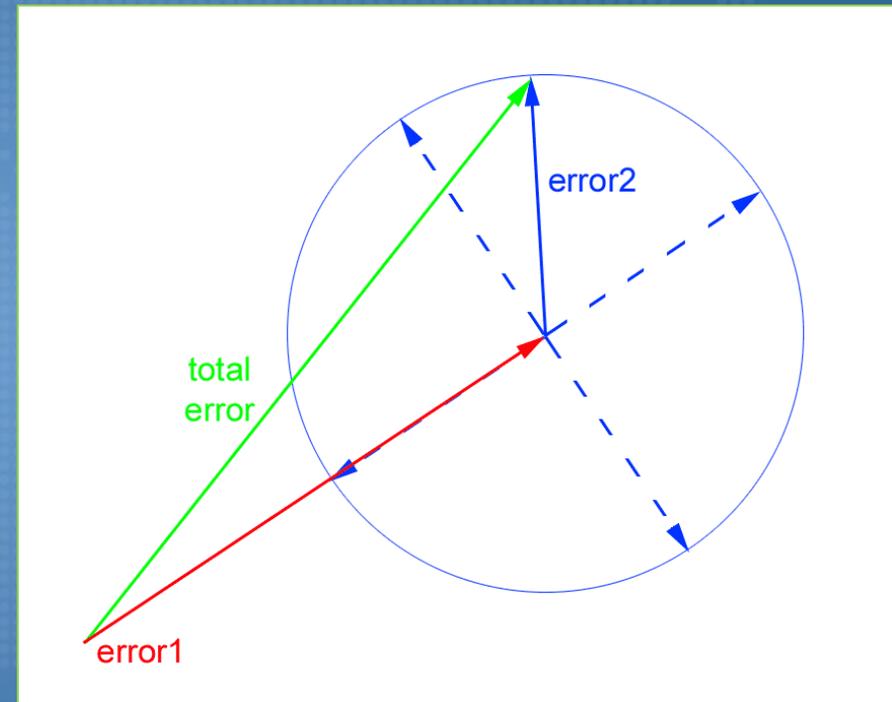
## RSS ANOTHER VIEW - 1

- Another way of visualizing why circular errors add up this way is to imagine a vector representing the first source of error. In the figure, this is the red arrow. Next, imagine another vector that starts at the tip of this first error, representing a second source of error; this is the blue arrow.
- If the second vector has exactly the same direction as the first, they add up. If it has the opposite direction, they subtract. If it is perpendicular, they add up by the Pythagorean Theorem, which is the same as a root sum square. If anywhere else, the vectors add up by the Law of Cosines; the green arrow represents the summation for the case of an arbitrary direction for the second error.



## RSS ANOTHER VIEW - 2

- If all directions of the second vector are equally likely (which they should be, given the assumptions of circularity and independence), then the weighted average of all possible directions will be the perpendicular case, which adds with the first as a root sum square. This analogy can be extended to any number of independent error vectors.
- It is useful to note with the sum of squares that the largest error tends to dominate the result. For example, if the error due to the vertical inaccuracy of the DEM is 10 meters and the only other error is 5 meters, the result is  $\sqrt{10^2 + 5^2} = 11.18$  meters, which is only 11.8% larger than the largest error.



# ERROR BUDGET CALCULATIONS

5	This worksheet will calculate the expected accuracy of an orthoimage, or a set of orthoimages											
7	Enter information in blue areas.											
8	Outputs are shown in red areas.											
11	<b>Project Information:</b>					<b>Horizontal (circular) error conversion</b>						
12	Project Name:				Alaska SDMI	input level:	90	CL % or RMSE				
14	Location:				Alaska	input error:	6.00	(m)				
15	Accuracy level (CL/LL %):				90	output level:	90	CL %				
16	What units do you want to use? Enter meters, feet, inches, or centimeters				meters	output error:	6.00	(m)				
18	<b>Satellite Information:</b>					<b>Vertical error conversion</b>						
20	Name of satellite:				KONOS	input level:	60	LL % or RMSE				
21	Source pixel size in meters:				1.00 (m)	input error:	7.00	(m)				
22	Maximum look angle in project area:				24.00 (deg)	output level:	90	LL %				
23	Error inherent in satellite model (CE90) with best method (e.g. RPOD) using ground control:				2.000 (m)	output error:	11.58	(m)				
24	Error inherent in satellite model/ephemeris (CLE90) with best method (e.g. RPOD) - satellite source dependent:				10.920 (m)							
33	<b>DFM Information:</b>											
35	Description of DFM:				5 DFM							
36	Vertical error (CF90):				11.58 (m)							
37	Horizontal error (CLE90):				0.00 (m)							
38	80th percentile of slope (can extrapolate from DFM):				0.00 (%)							
40	<b>Orthorectification:</b>					<b>Minimum ground control recommendations</b>						
42	Are you using ground control? Enter Y or N				y	Quick2d:	10x10 km					
44	If using ground control - follow minimum ground control recommendations at right					KONOS:	10x50 km, min. 2 per strip					
45	Circular accuracy (CLE90) of ground control:					10.920 (m)	SPO:	10 points per scene				
46	Photo identifiable precision of ground control (use 0.9 pixel if good):					1.000 (input pix)	Other:	check with vendor				
48	<b>Predicted circular accuracy of orthorectified product:</b>											
50	Error due to vertical accuracy of DFM:				0.156 (m)							
51	Error due to horizontal accuracy of DFM:				0.000 (m)							
52	Error due to ground control circular error:				10.920 (m)							
53	Error due to ground control photo-ident. flexibility:				1.000 (m)							
54	Error due to satellite model:				2.000 (m)							
55	Predicted circular accuracy (CF90):				12.263 (m)							
56	CL90/NMA's error:				12.263 (m)							
57	CF90/NASA error:				14.613 (m)							
58	NMA's scale:				1: 24,145							

## ERROR BUDGET SPREADSHEET

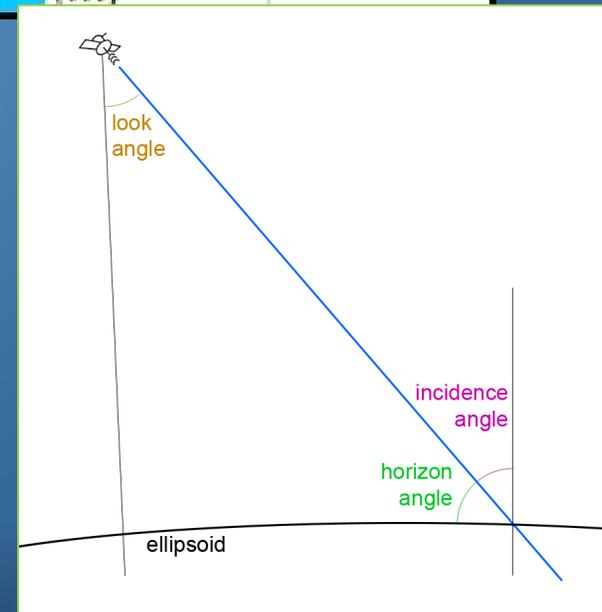
- If evaluating for National Map Accuracy standards, 90% should be used, whereas if evaluating for NSSDA, 95% should be used. Use 63.21% for an RMSE or 1-sigma standard, or 50% for the average error.

<b>Project information:</b>	
Project Name:	Alaska SDMI
Location:	Alaska
Accuracy level (CE/LE %):	95
What units do you want to use? Enter meters	meters

# ERROR BUDGET SPREADSHEET

- The third field (F22) represents the maximum expected incidence angle from the satellite to the ground. If the spreadsheet is to be used for an error budget for a single image of known incidence angle, enter that here.

Satellite information:			
Name of satellite:		IKONOS	
Source pixel size in meters:		1.00	(m)
Maximum incidence angle in project area:		24.00	(deg)
Error inherent in satellite model (CE95) with be		2.000	(m)
Error inherent in satellite model/ephemeris (		10.000	(m)



## ERROR BUDGET SPREADSHEET

- The fourth field (F23) may be the most difficult to determine. This is the error inherent in the satellite model using the best orthorectification model. For example, a typical algorithm used in orthorectification software is the “rigorous” model, which takes into account the physical characteristics of the sensor. The error reported in this field represents the uncertainty in the model of satellite position, attitude, and camera model, even if the DEM and ground control are perfect.

Satellite information:			
Name of satellite:		IKONOS	
Source pixel size in meters:		1.00	(m)
Maximum incidence angle in project area:		24.00	(deg)
Error inherent in satellite model (CE95) with best available data:		2.000	(m)
Error inherent in satellite model/ephemeris (CE95):		10.000	(m)

## ERROR BUDGET SPREADSHEET

- Cell F24 is used to report the error inherent in the satellite model using the best method available when ground control is *not* used. Typically, this would be a model that uses rational polynomial coefficients, or RPCs. Most vendors provide RPCs with their non-orthorectified (“basic”) imagery, and they often will quote a number that represents the accuracy you can expect using RPCs without ground control.

Satellite information:			
Name of satellite:		IKONOS	
Source pixel size in meters:		1.00	(m)
Maximum incidence angle in project area:		24.00	(deg)
Error inherent in satellite model (CE95) with best ground control:		2.000	(m)
Error inherent in satellite model/ephemeris (no ground control):		10.000	(m)

# ERROR BUDGET SPREADSHEET

- The vertical error field (F36) should contain the quoted vertical error of the DEM, also known as LE (linear error) at a certain value. The percentile used is the same as what is defined in cell F15.
- If you are given a different value from the percentile that is asked for, use the vertical error conversion form at the right to perform this conversion. Type in the word “RMSE” if you know the RMSE (root mean square error) of the data, otherwise type in a percentage value, such as “90” or “95” in cell K19. Next, type the value of given number in cell K20 (example: CE90 of 4.5 meters means “90” goes into K19 and “4.5” goes into K20). The calculated vertical error at the given level (the same level used for the entire sheet) is given in cell K22.

DEM information:			
Description of DEM:			G-DEM
Vertical error (LE95):		11.58	(m)
Horizontal error (CE95):		0.00	(m)
95th percentile of slope (can extrapolate from		0.	

Vertical error conversion		
input level	90	LE % or RMSI
input error	1000.00	(m)
output leve	95	LE %
output erro	1191.57	(m)

## ERROR BUDGET SPREADSHEET

- The last field in this section (F38) is the  $X^{\text{th}}$  percentile of slope over the project area, where  $X$  is the accuracy level defined in cell F15. Note that this field is only relevant if the horizontal error in cell F37 is non-zero. To determine this value, it may be necessary to build a DEM for the project area, perform a slope analysis, and determine the  $X^{\text{th}}$  percentile by analyzing the histogram. Use the best freely-available DEM, as coarse datasets like SRTM30 will tend to underestimate the slope values in a much higher resolution elevation model.

DEM information:			
Description of DEM:		G-DEM	
Vertical error (LE95):		11.58	(m)
Horizontal error (CE95):		0.00	(m)
95th percentile of slope (can extrapolate from		0.00	(%)

## ERROR BUDGET SPREADSHEET

- If GCPs are used, enter the circular accuracy of the ground control at the X<sup>th</sup> percentile in the first field (F45), where X is the accuracy level defined in cell F15. This number should be provided by the ground control supplier. If survey points are the primary source of control, the quoted accuracy of those points should be entered here. If high-resolution imagery is to be used, enter the circular accuracy of this imagery in this field.

Orthorectification:			
Are you using ground control? Enter Y or N		y	
<i>If using ground control - follow minimum ground control recommendations at right</i>			
Circular accuracy (CE95) of ground control		1.000	(m)
Photo-identifiable precision of ground control		1.000	(input pix)

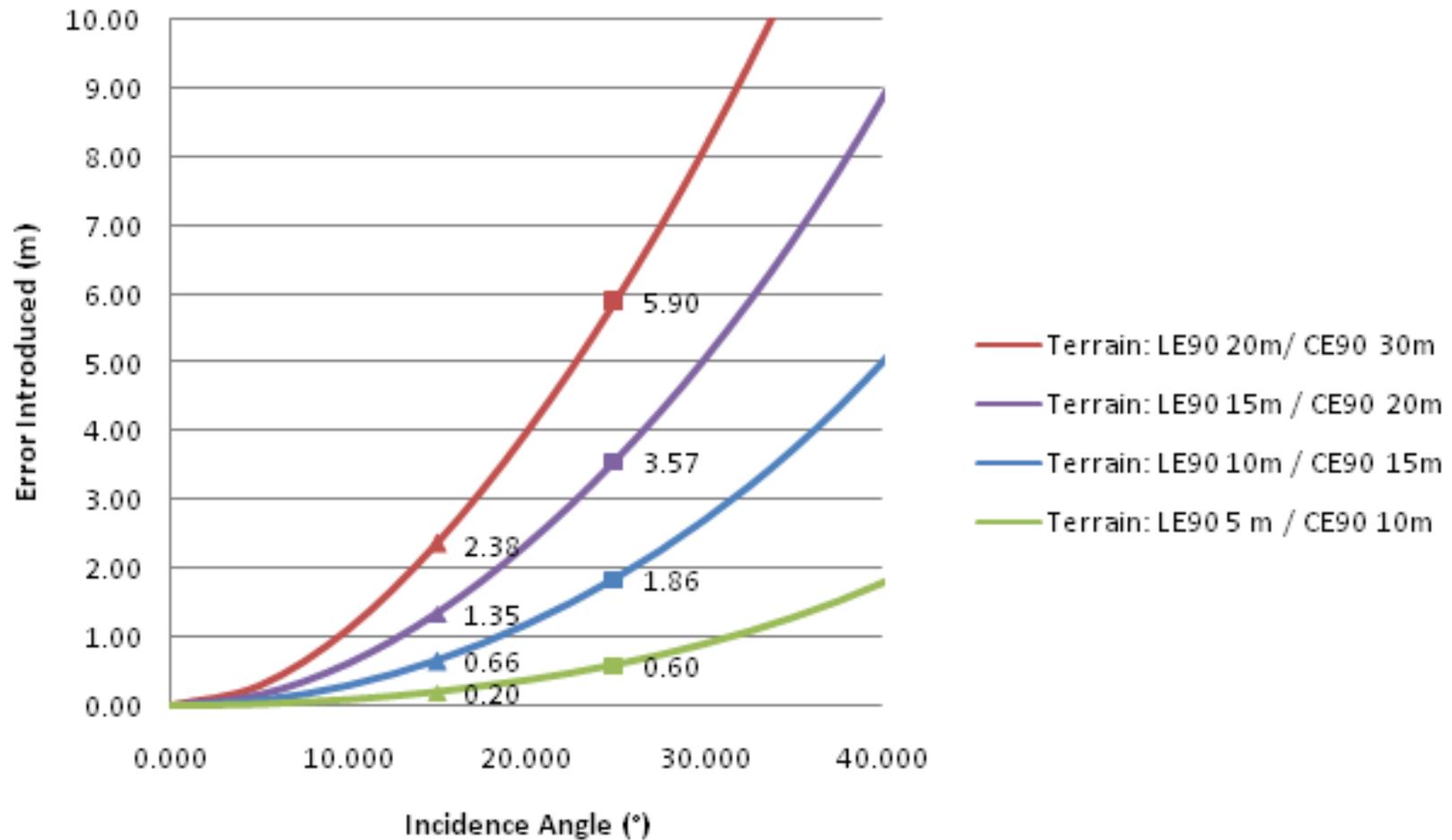
# ERROR BUDGET SPREADSHEET

## *Predicted circular accuracy of orthorectified product:*

Error due to vertical accuracy of DEM:	5.156	(m)
Error due to horizontal accuracy of DEM:	0.000	(m)
Error due to ground control circular error:	1.000	(m)
Error due to ground control photo-identifiability:	1.000	(m)
Error due to satellite model:	2.000	(m)
<b>Predicted circular accuracy (CE95):</b>	<b>5.708</b>	<b>(m)</b>
CE90/NMAS error	4.790	(m)
CE95/NSSDA error	5.708	(m)
NMAS scale 1:	6,742	

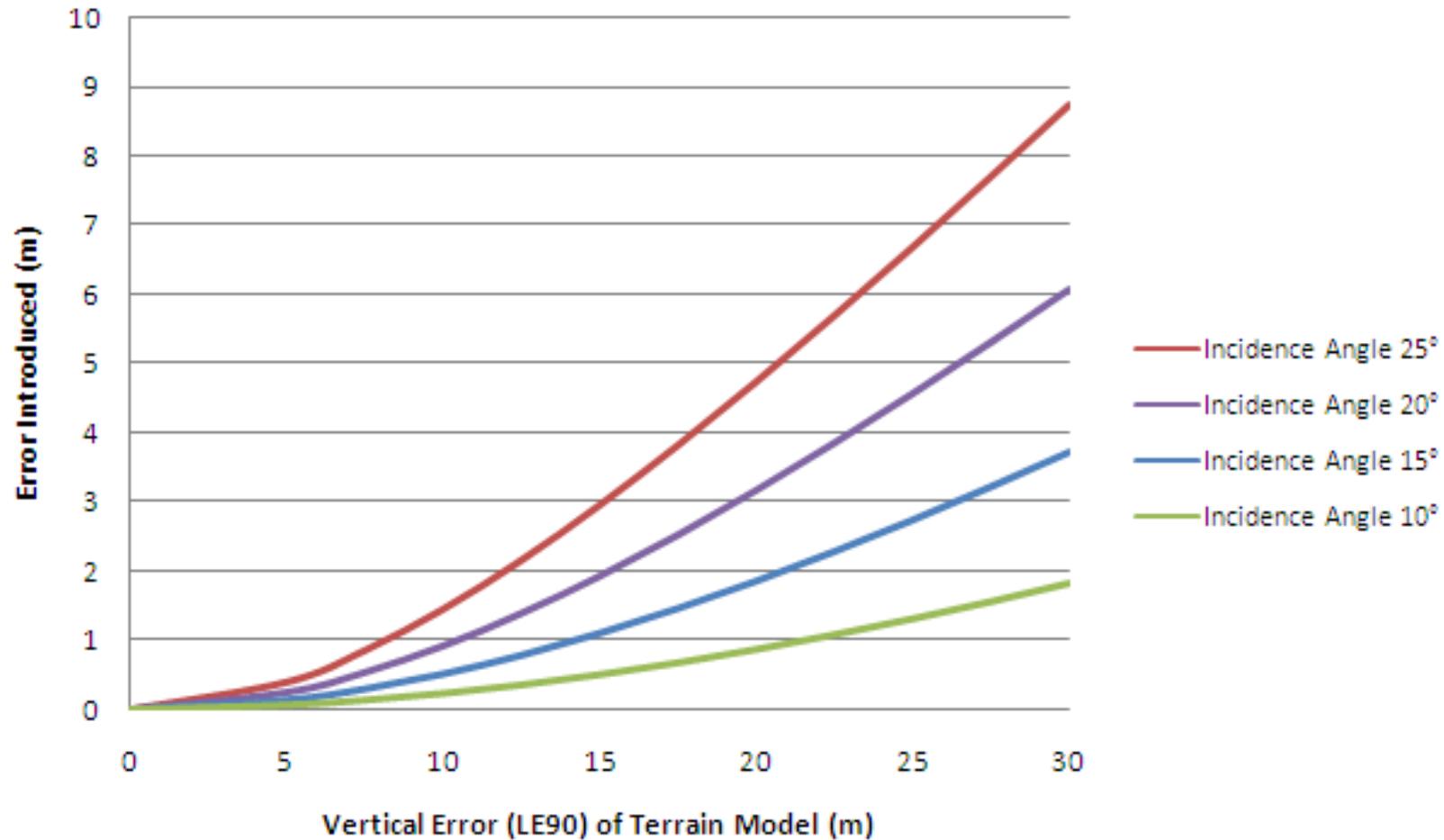
# ERROR INTRODUCED BY INCIDENCE ANGLE

**Error Introduced by Incidence Angle:**  
**Diminishes with Increased Accuracy of the Terrain Model Utilized**



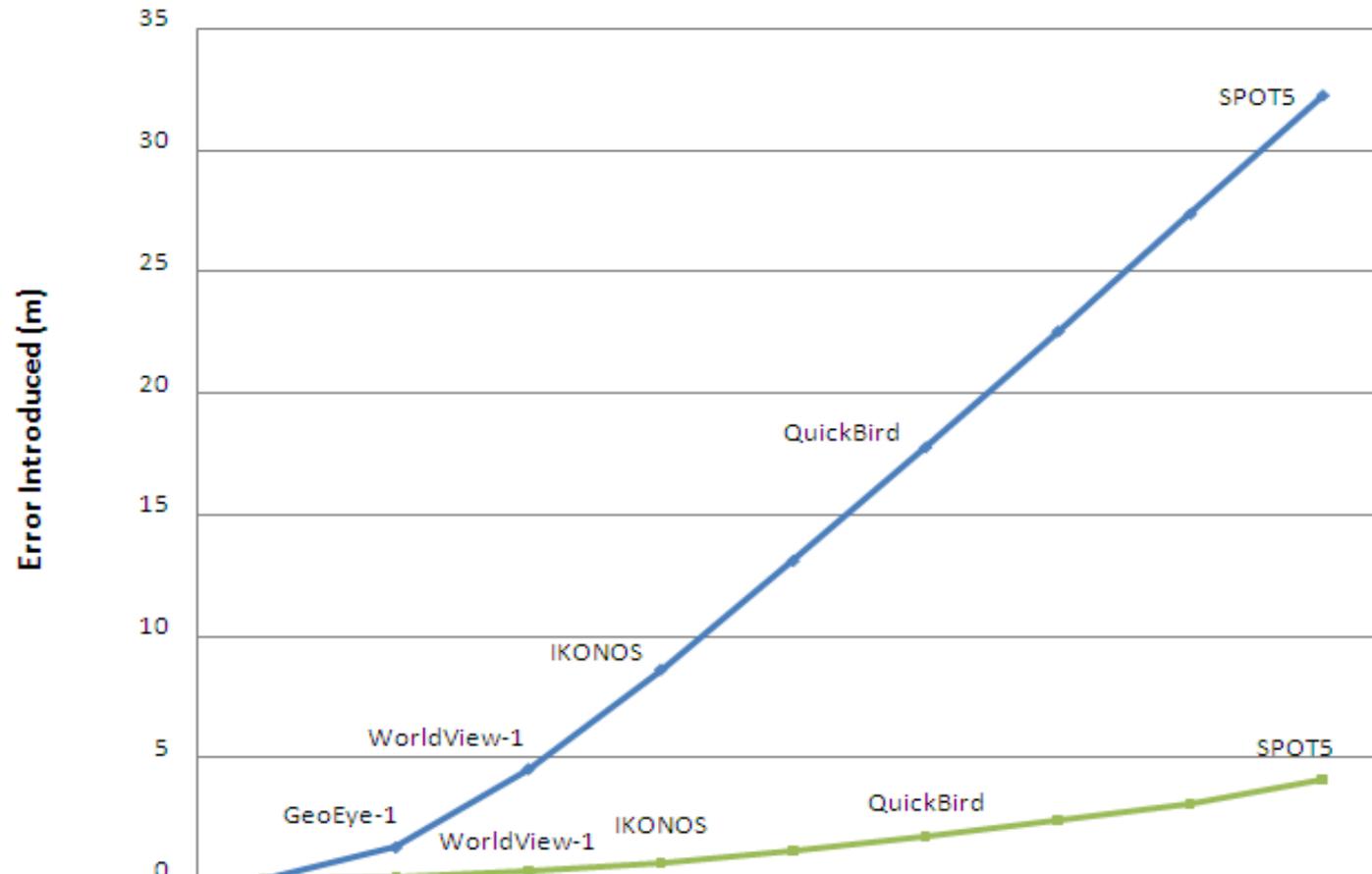
# RESTRICT INCIDENCE ANGLE OF IMAGE ACQUISITION

**Error Introduced by Vertical Error of Terrain Model:**  
reduced by decreasing incidence angle of imagery



# IMPROVEMENT WITH GROUND CONTROL

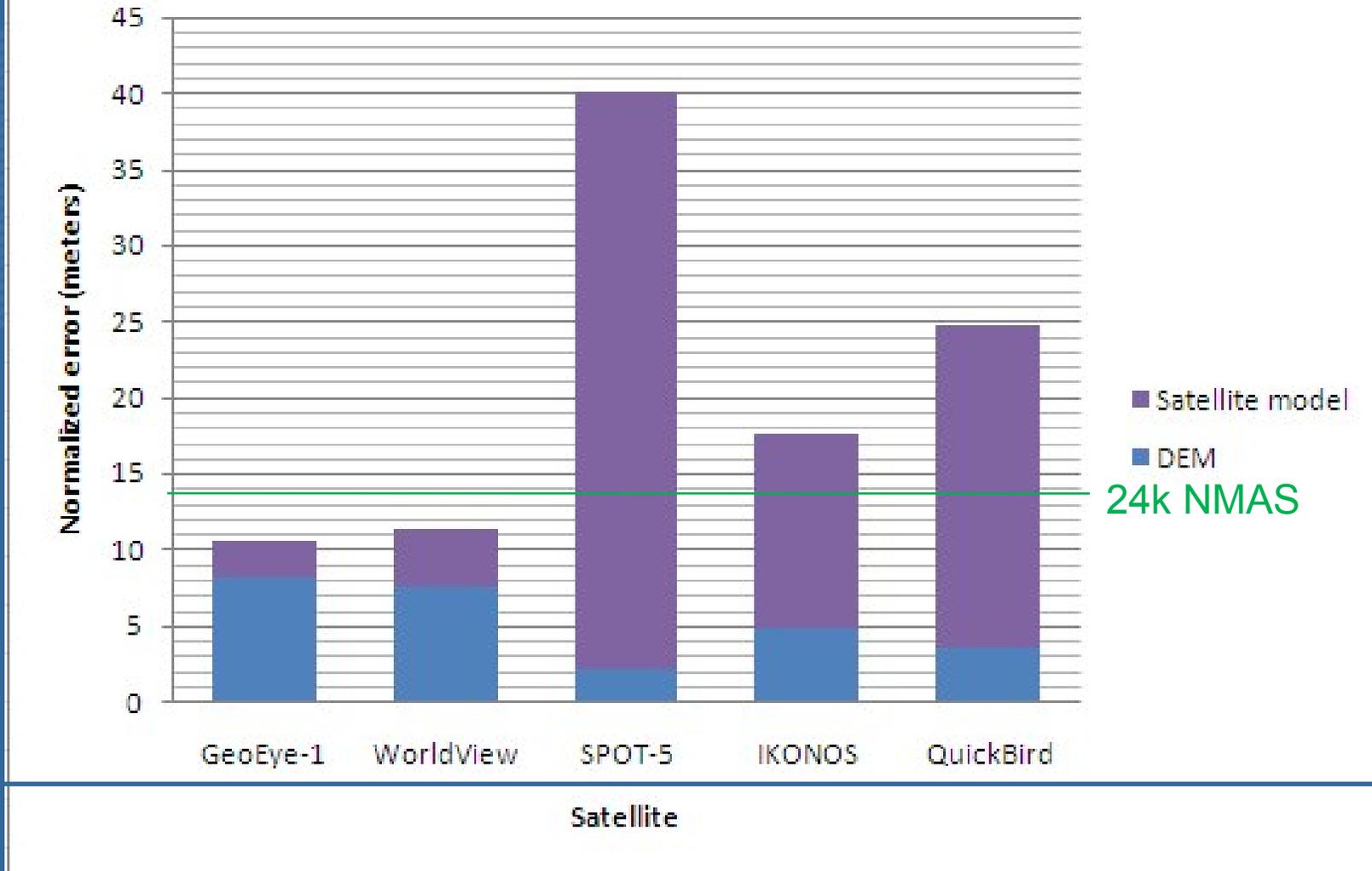
## Error Introduced by Native and Improved Accuracy



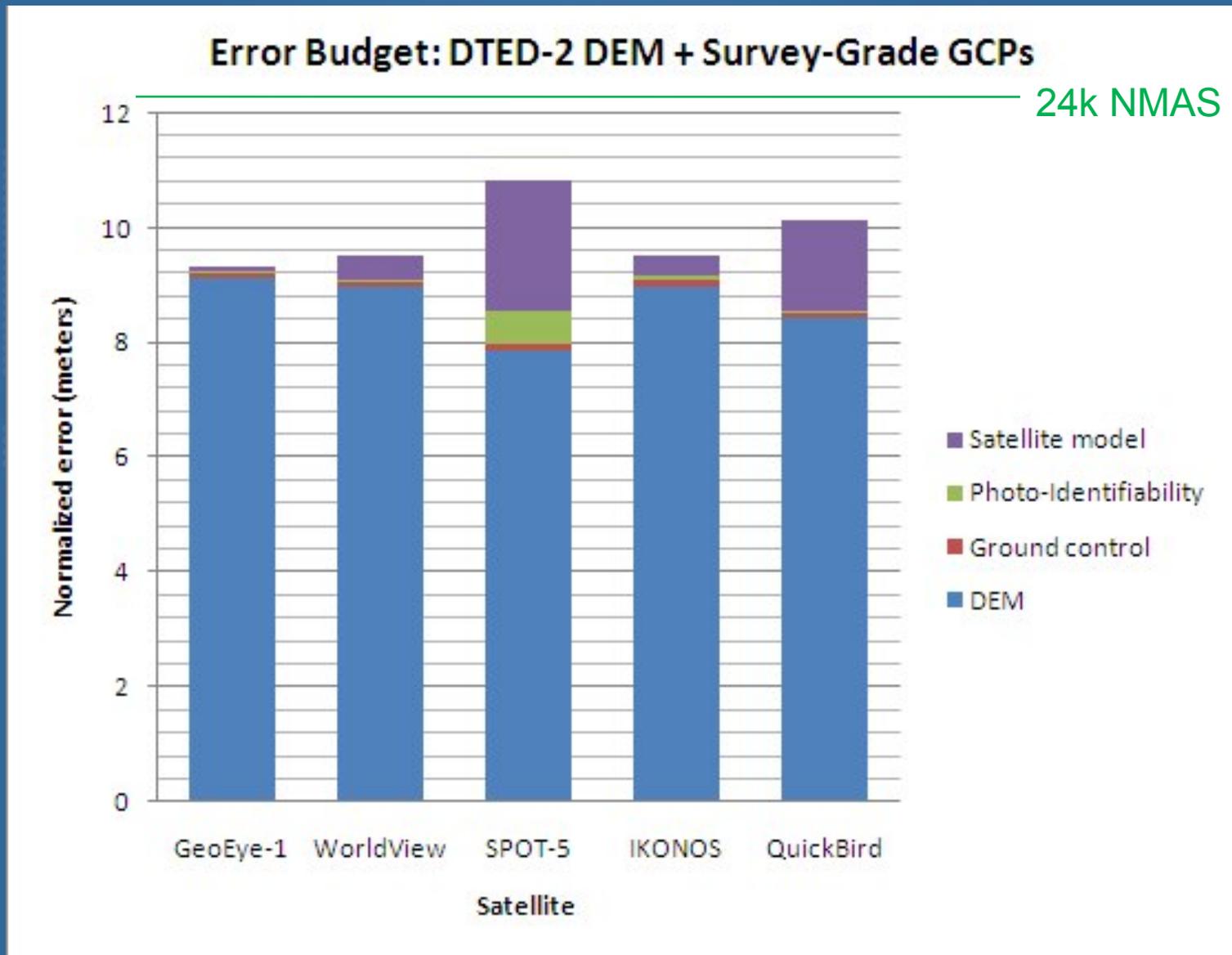
Native Accuracy (m)	0	1.336	4.557	8.644	13.114	17.775	22.54	27.37	32.24
Improved Accuracy (m)	0	0.0993	0.373	0.703	1.181	1.758	2.417	3.145	4.116

# ERROR BUDGET SPREADSHEET

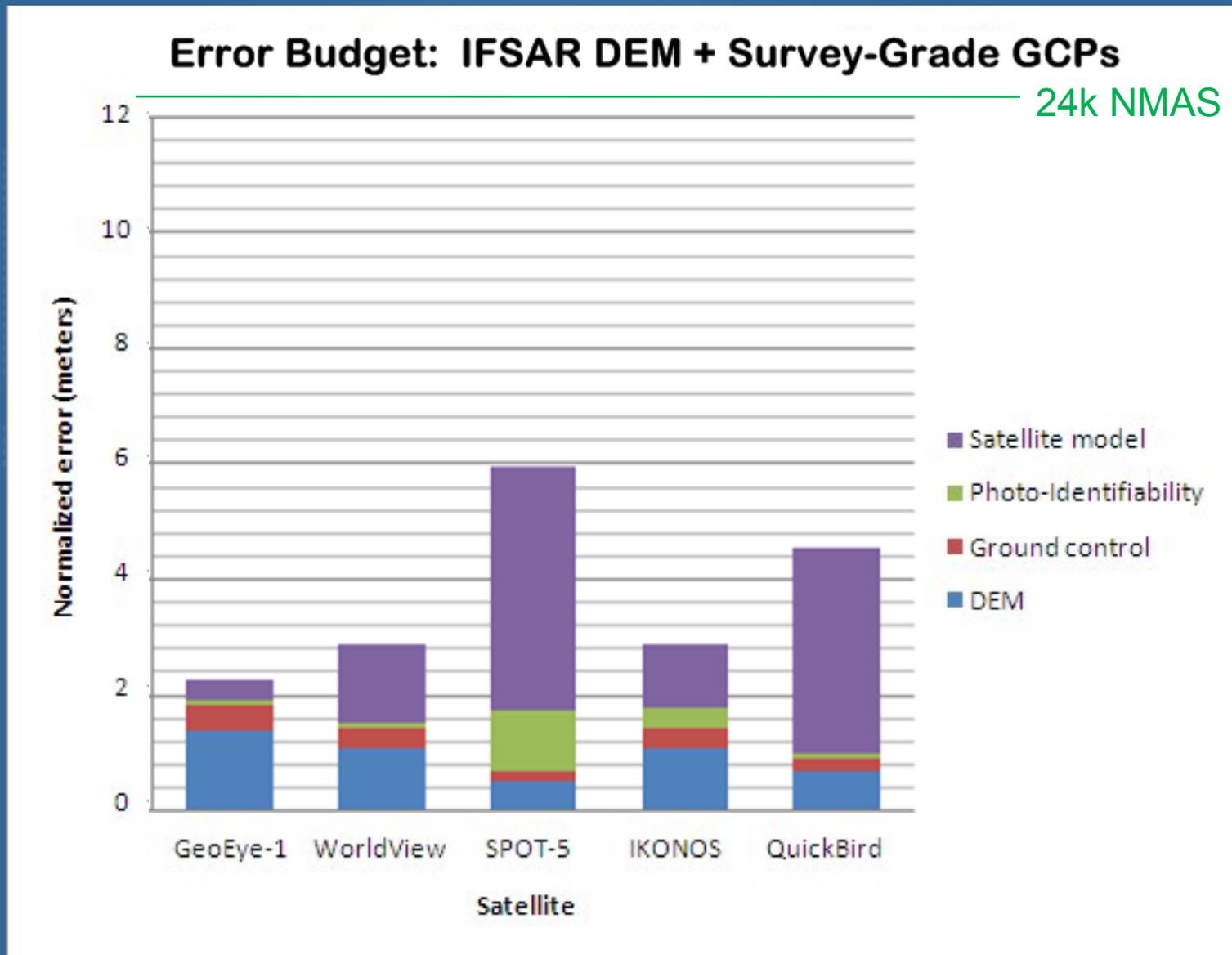
## Error Budget: DTED-2 DEM without GCPs

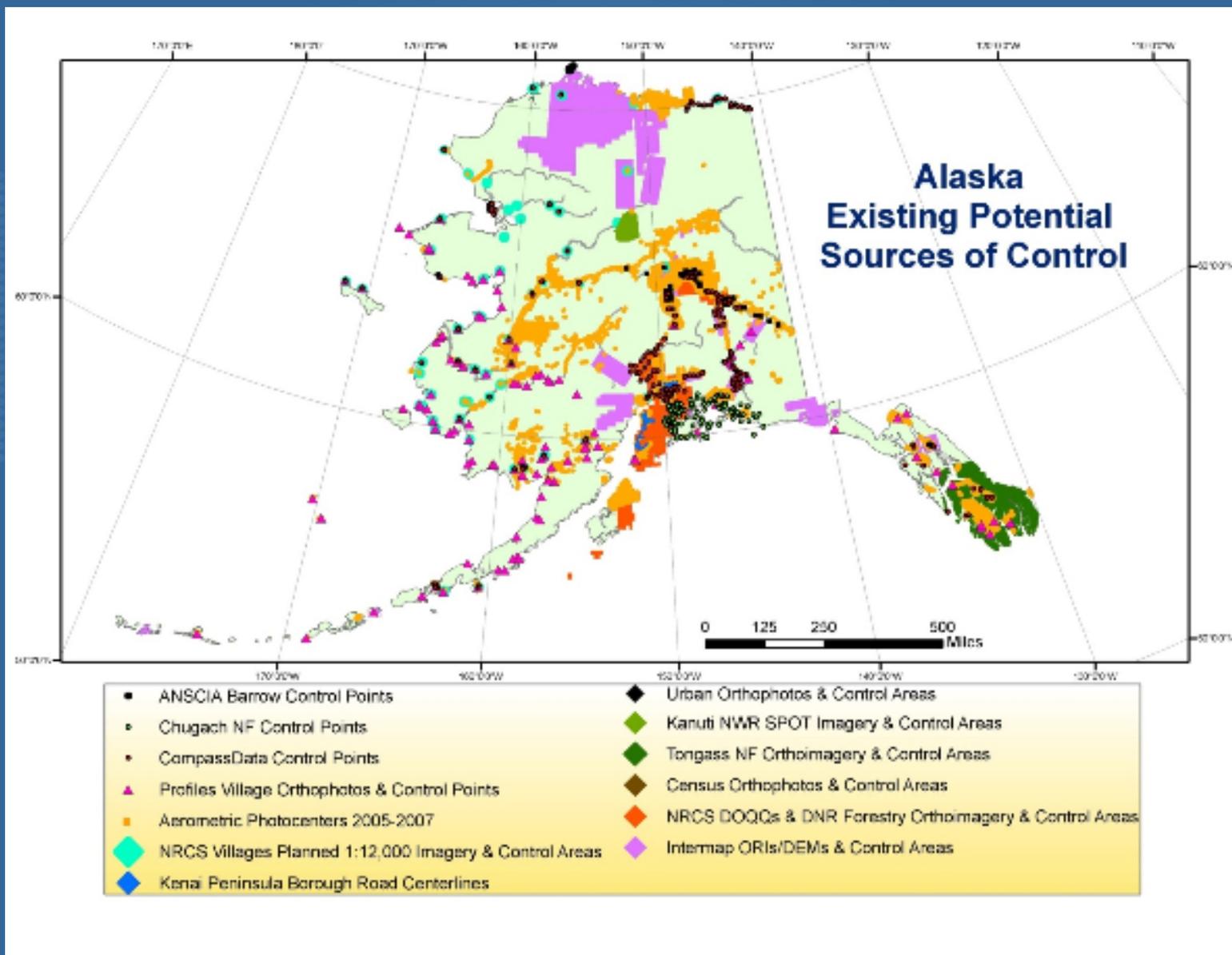


# ERROR BUDGET SPREADSHEET

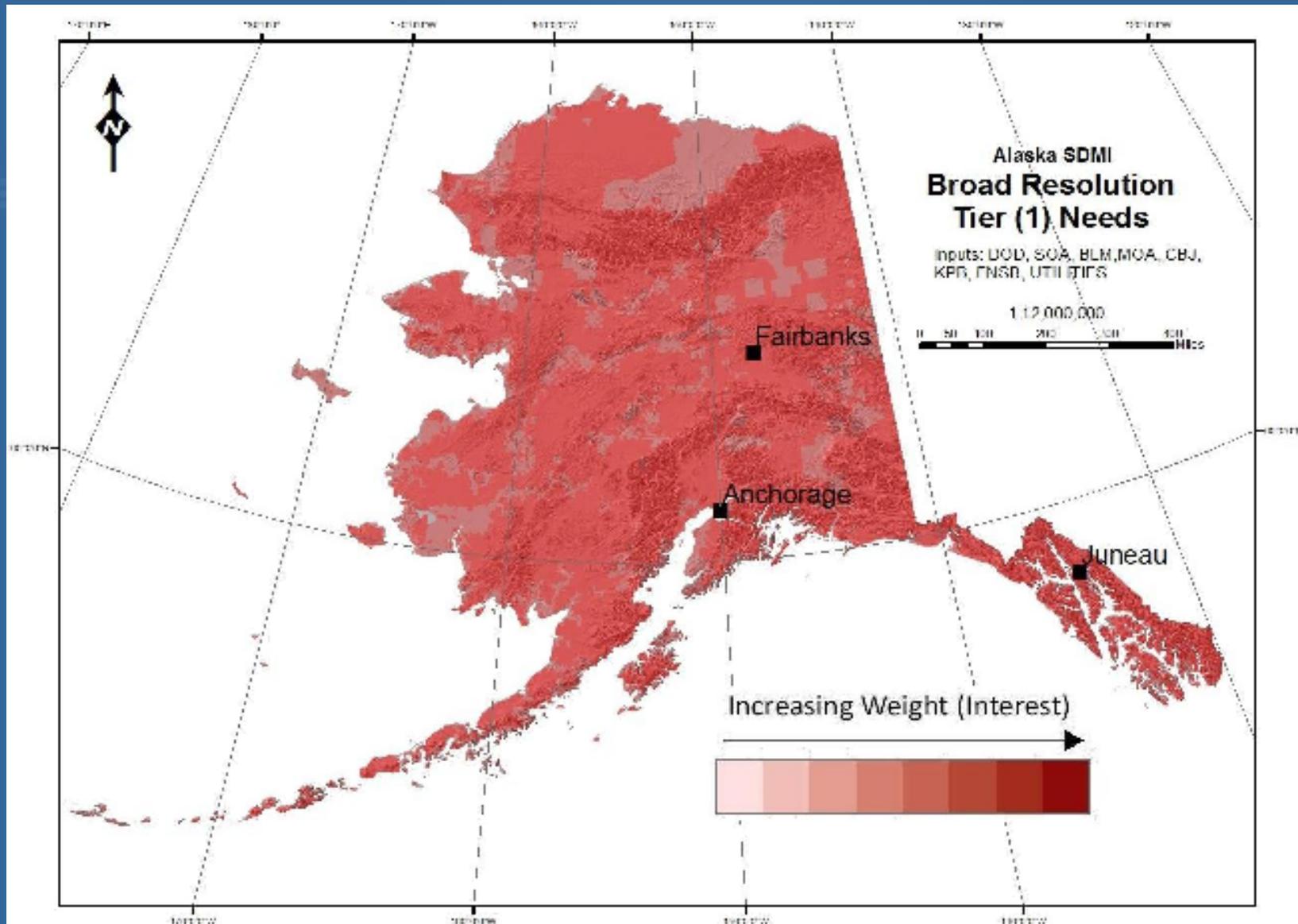


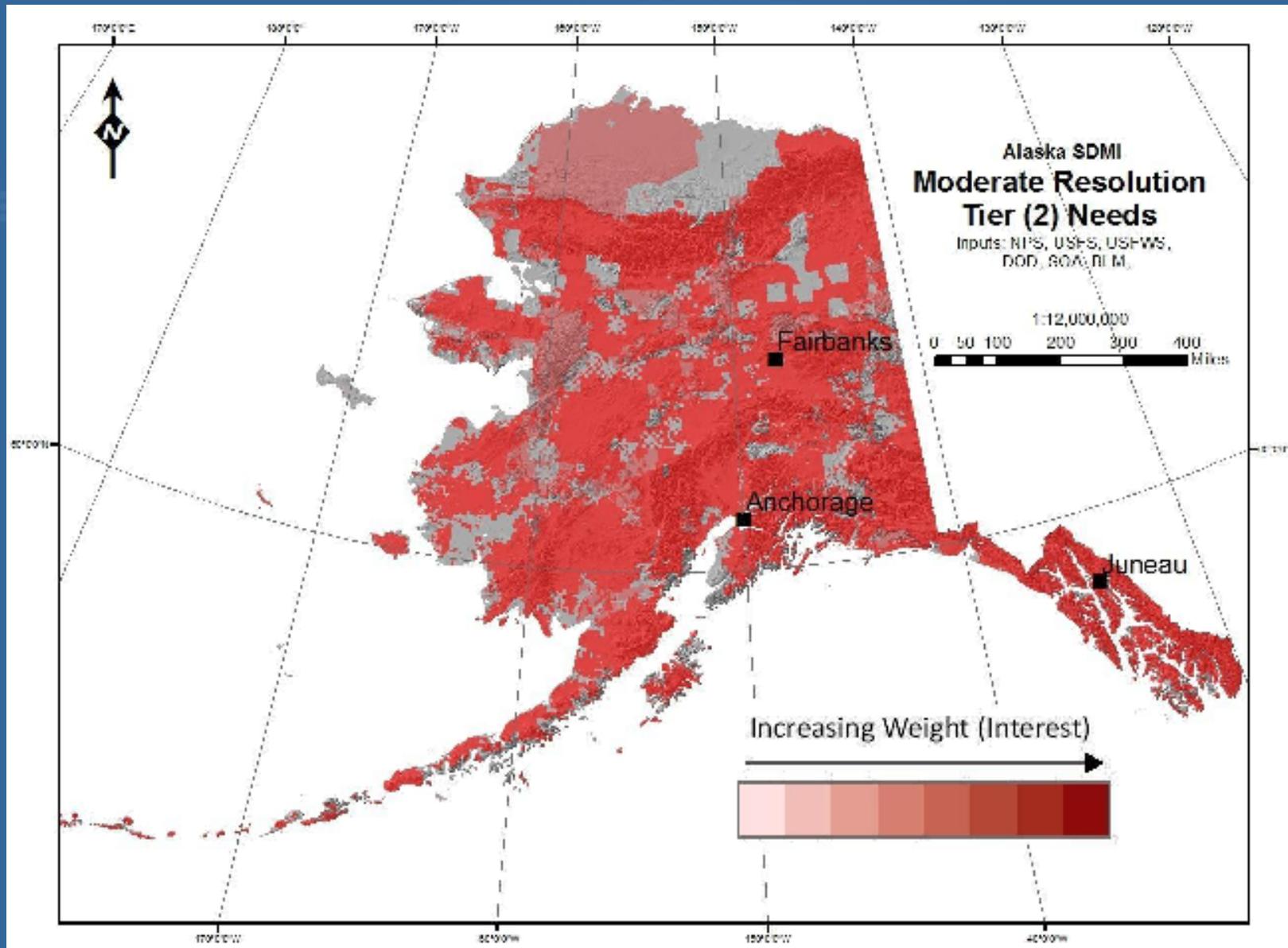
# ERROR BUDGET SPREADSHEET

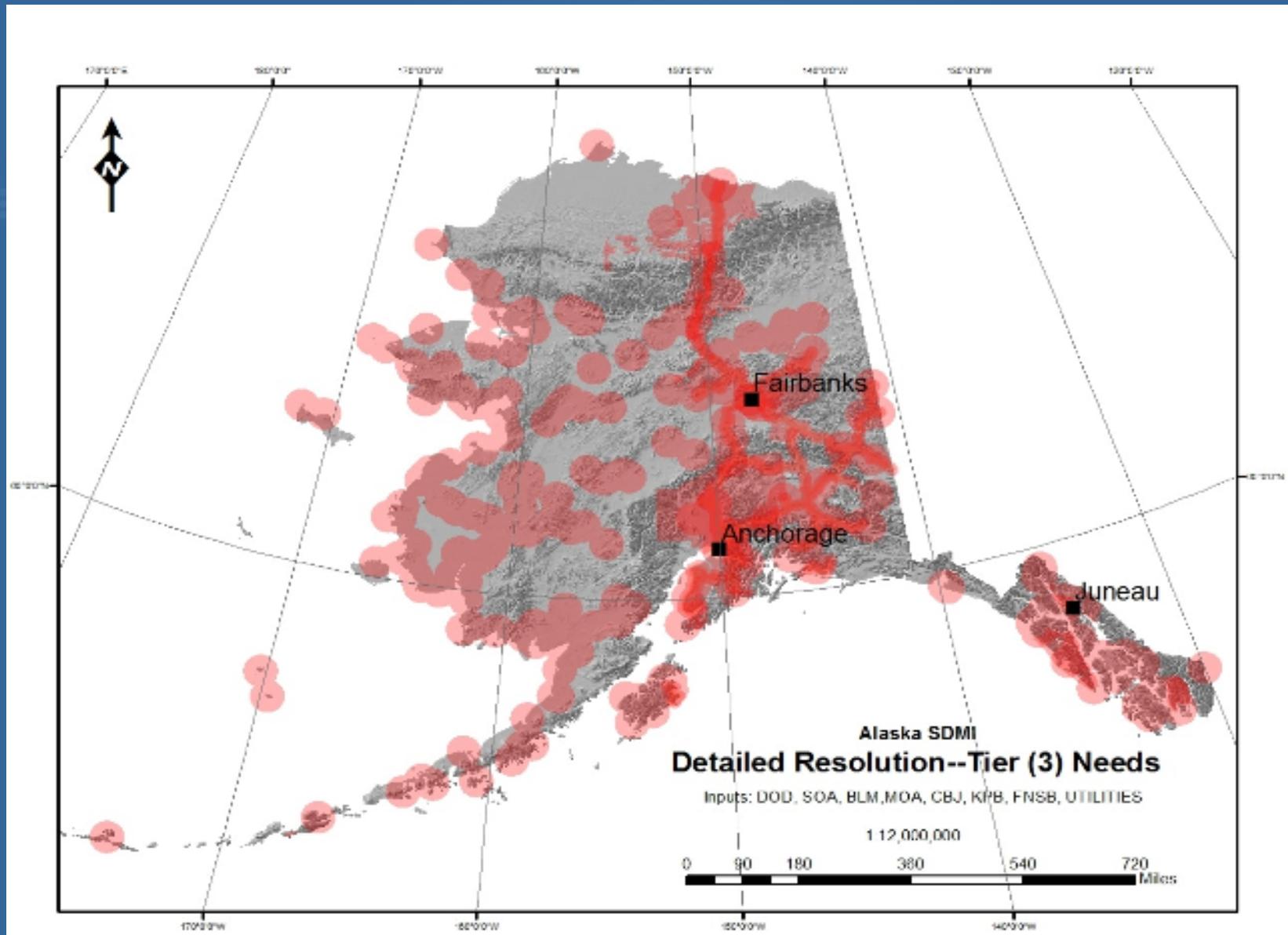




Agency/Organization	Imagery Area Requirements by Scale/Resolution					
	Broad (2.5-10 meter)		Moderate (1-2.5 meter)		Detailed (sub- to 1-meter)	
	Area (sq. km.)	% of State	Area (sq. km.)	% of State	Area (sq. km.)	% of State
Federal Aviation Administration, ADOT Aviation	1,493,266	100	-	-	155,245	12
US Department of Defense	-	-	8,498	1	234,523	16
National Wetlands Inventory (USFWS)	1,493,266	100	-	-	-	-
USFWS	1,493,266	100	290,343	19	-	-
Bureau of Land Management	1,493,266	100	209,758	14	33,936	2
National Park Service	203,342	14	203,342	14	-	-
USDA Forest Service	1,493,266	100	-	-	85,942	6
State of Alaska (including ADOT), Alaska Railroad Corp.	1,493,266	100	413,180	28	305,912	20
Native Corporations & Organizations	1,493,266	100	-	-	174,650	12
Boroughs, Municipalities, Cities	-	-	528,234	35	104,990	7
Populated Places (Municipalities, Cities, Villages) - Buffered 10 km	-	-	-	-	229,299	15
Major Roads & Railroads - Buffered 5 km	-	-	-	-	58,020	4
Trans-Alaska Pipeline & Other Pipelines - Buffered 10 km	-	-	-	-	25,223	2
Utilities & Infrastructure	-	-	-	-	55,541	4
<b>NON-OVERLAPPING AREA TOTALS</b>	1,493,266	<b>100</b>	1,205,591	<b>81</b>	409,062	<b>27</b>







## CONCLUSIONS

- **This is a statewide program serving State, Federal, Alaska Native and other stakeholders.**
- **A 1:24,000 scale image map, 2.5m – 5m resolution, multi-spectral, updated no less often than every 3 - 5 years is a consensus requirement.**
- **All existing commercial systems can meet the 1:24k requirement with adequate DEM and ground control given collection geometry constraints.**
- **Larger scale image maps (higher resolution) will be required for regional 1m – 2.5m or project 0.5m – 1m work.**
- **Swath / footprint size matters to classification applications (wetland delineation, fire fuel modeling etc.) based on spectral continuity.**
- **Orthorectification and mosaicking costs are not insignificant.**
- **Some applications require leaf-off or stereo imagery.**
- **Ground receiving stations (virtual or real) provide benefits.**



*questions*