



Innovative Imaging & Research

Radiometric Correction Workflow for Aerial Imaging Applications

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Joint Agency Commercial Imagery Evaluation
Civil Commercial Imagery Evaluation Workshop

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Aerial Imaging Market Forces

- ▶ Drive to increase acquisition efficiency to reduce overall operation costs
 - Fly at higher altitudes to increase coverage
- ▶ Drive to increase operational flight envelope to maximize flight opportunities
 - Fly at non-optimum illumination and atmospheric conditions



Camera Focal Plane Technology Advancements

- ▶ Camera focal planes are evolving to meet this demand
 - Array size is increasing
 - Pixel size is decreasing

	DMC I	DMC IIe 140	DMC IIe 230	DMC IIe 250
PAN No. of Pixels	13,824 x 7,680	12,096 x 11,200	15,552 x 14,400	16,768 x 14,656
PAN Pixel Size	12 μm	7.2 μm	5.6 μm	5.6 μm
PAN Focal length	120 mm	92 mm	92 mm	112 mm
Pan Cross-track FOV	69.3 deg	50.7 deg	50.7 deg	45.5 deg

As Pixel Size Decreases...

- ▶ As pixel size (pitch) decreases
 - The well capacity decreases and the number of photons striking a detector decreases
 - This in turn drives down the total attainable signal for each pixel and decreases the SNR
- ▶ The need to understand a sensor's noise properties increases
 - Radiometric calibration becomes essential
 - Enables advanced denoising algorithms

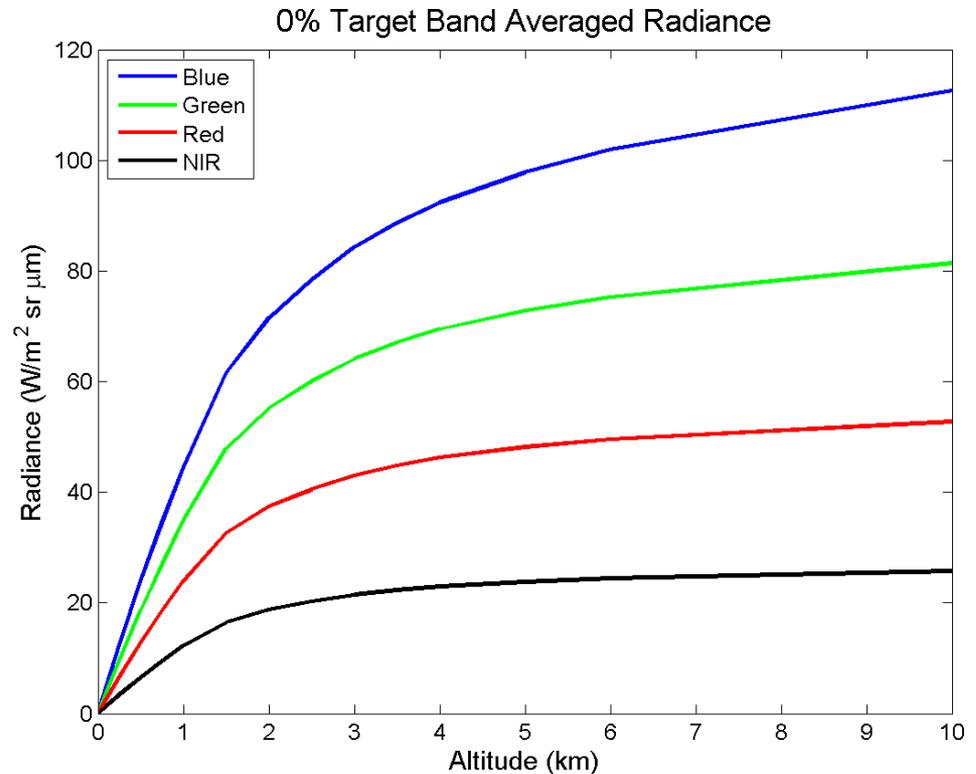
Higher Flight Altitudes Means...

- ▶ There's a lot more atmosphere between the sensor and the ground
 - Gaseous molecules – N_2 , O_2 , Ar, Ne, He, Kr, CO_2 , H_2O , CH_4 , NO , N_2O , NO_2 ...
 - Aerosols – fine solid particles such as dust, air pollutants and smoke



Atmosphere

- ▶ The atmosphere is anisotropic – not uniform
 - Varies 3-D
- ▶ Most of the atmosphere is below 8–10 km
- ▶ Pilots require oxygen above ~4km

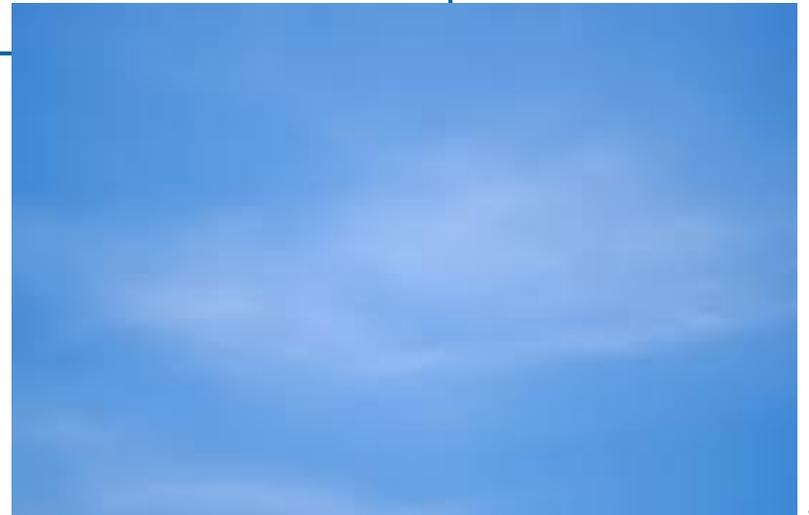


0% reflectance target means the entire signal comes from the atmosphere

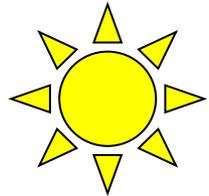
Atmosphere

“In most cases, the atmosphere is perceived as a hostile entity whose adverse impacts must be neutralized or eliminated before remotely sensed data can be properly analyzed.”

(Schott, “Remote Sensing: The Image Chain Approach”, 1997)



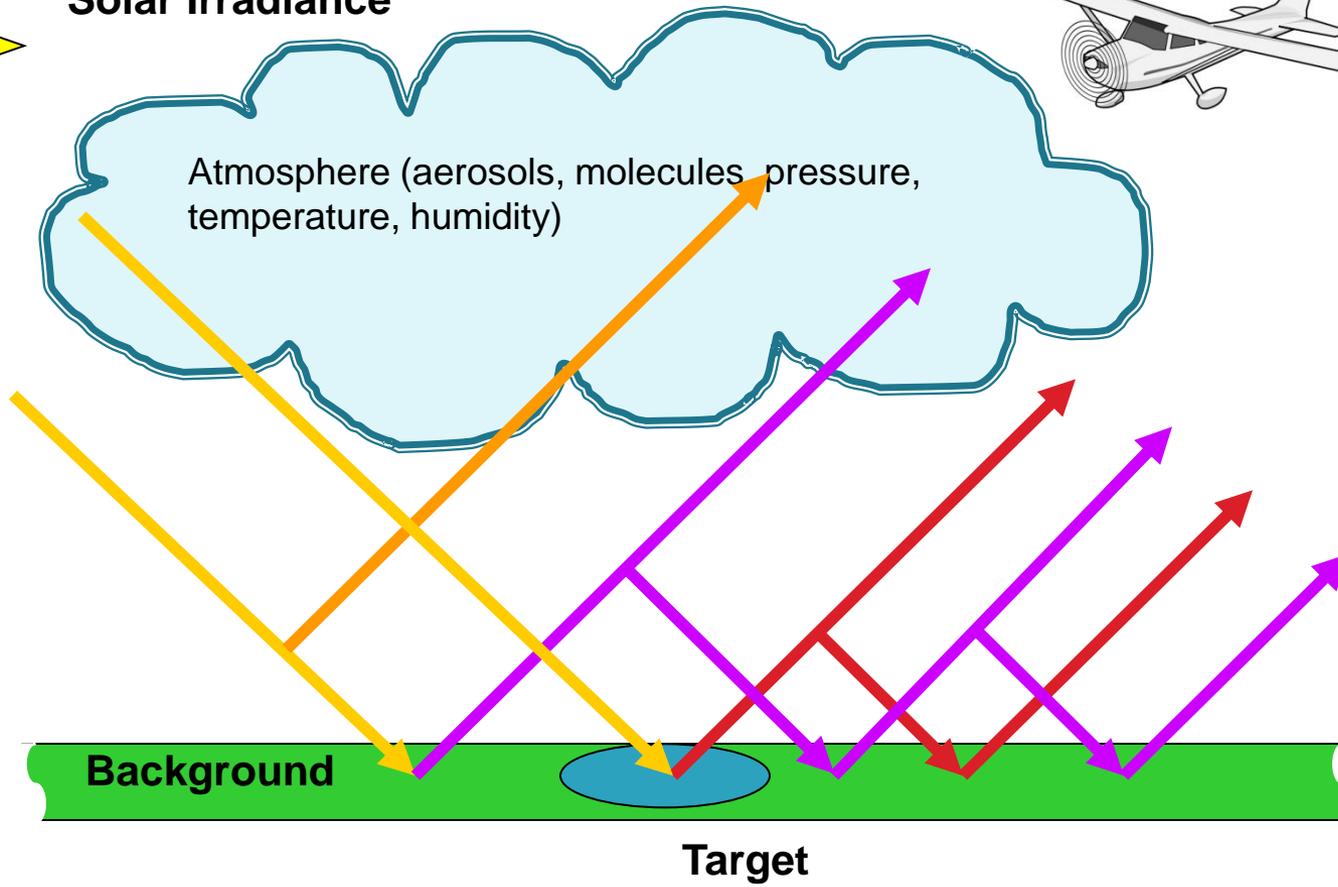
What a Sensor Sees



Solar Irradiance



Sensor



Simulated Image Products – Image Zoomed to View Identical Features



Stennis
Space
Center

Modtran
based rural
atmosphere

High
Visibility



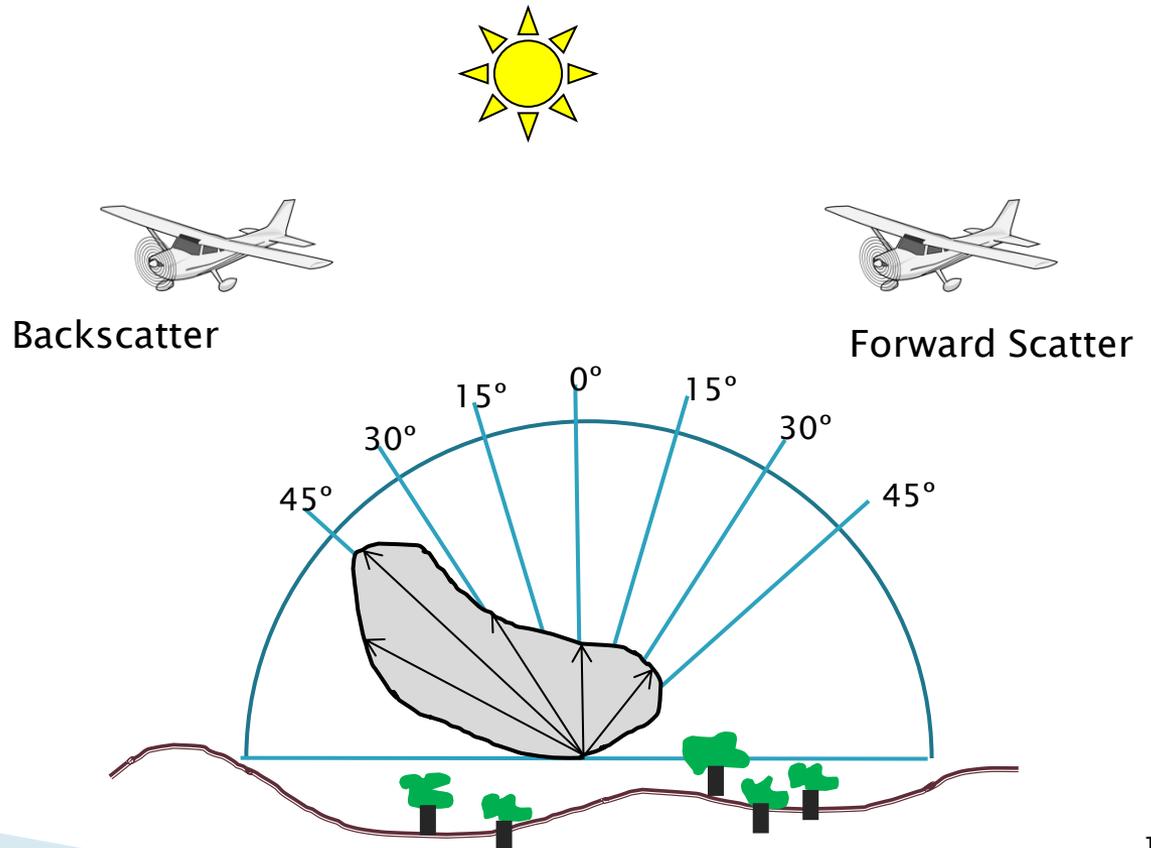
Baseline imagery courtesy of Midwest Aerial Photography

Bidirectional Reflectance

- ▶ Both the solar and sensor viewing geometry also effect how a target looks



Blue band - Tampa FL
Imagery courtesy of Quantum Spatial



BRDF Example

Aged Asphalt Road

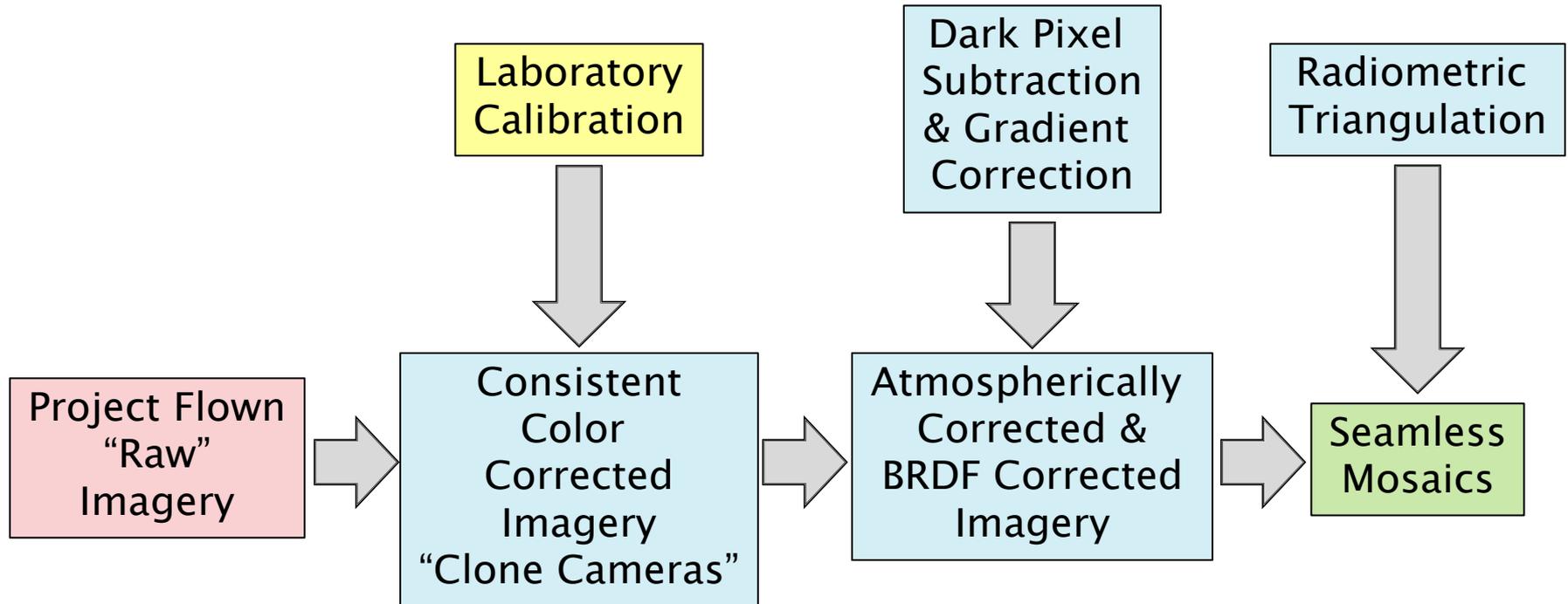


Forward Scatter –
Sun in front of
camera



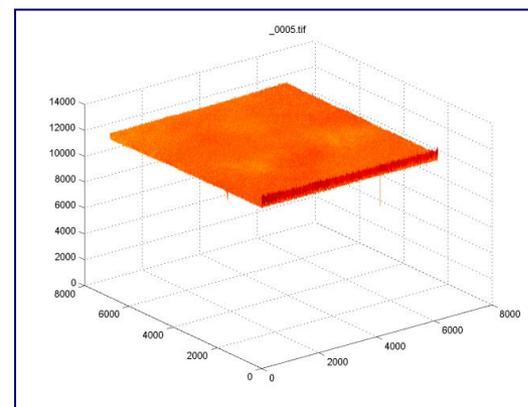
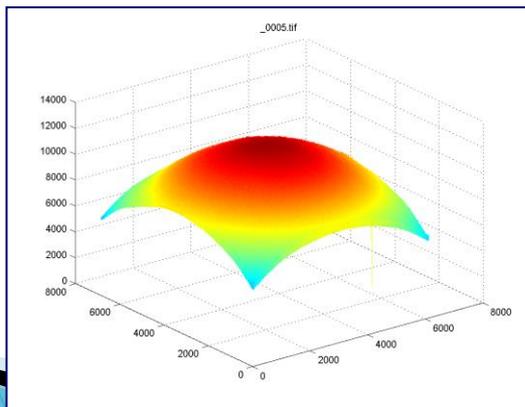
Back Scatter –
Sun behind
camera

Automated Radiometric Workflow



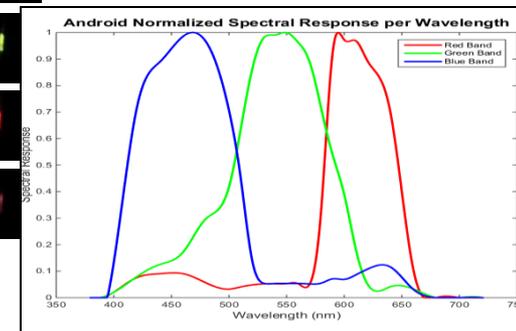
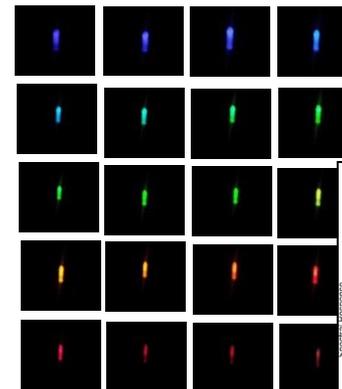
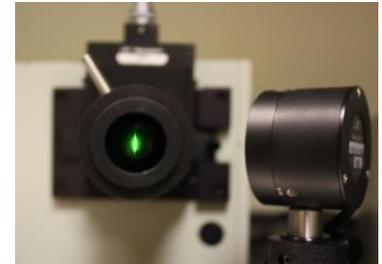
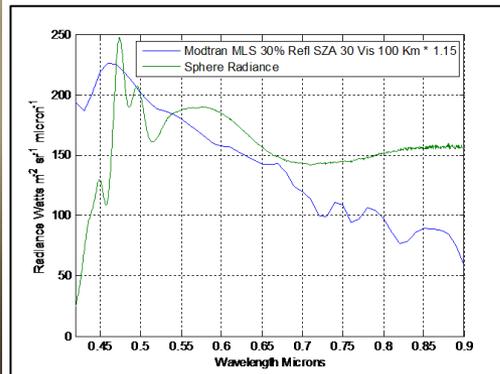
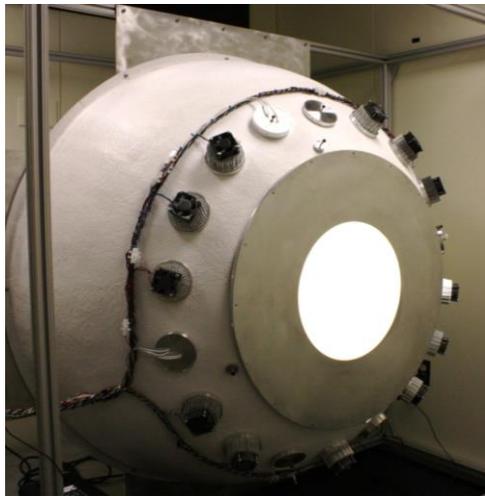
Laboratory Calibration

- ▶ Relative Radiometric Calibration
 - Dark frame characterization
 - Flat fielding
 - Defective pixel identification and replacement
 - Signal-to-noise ratio evaluation
 - Linearity assessment
 - Shutter variability assessment

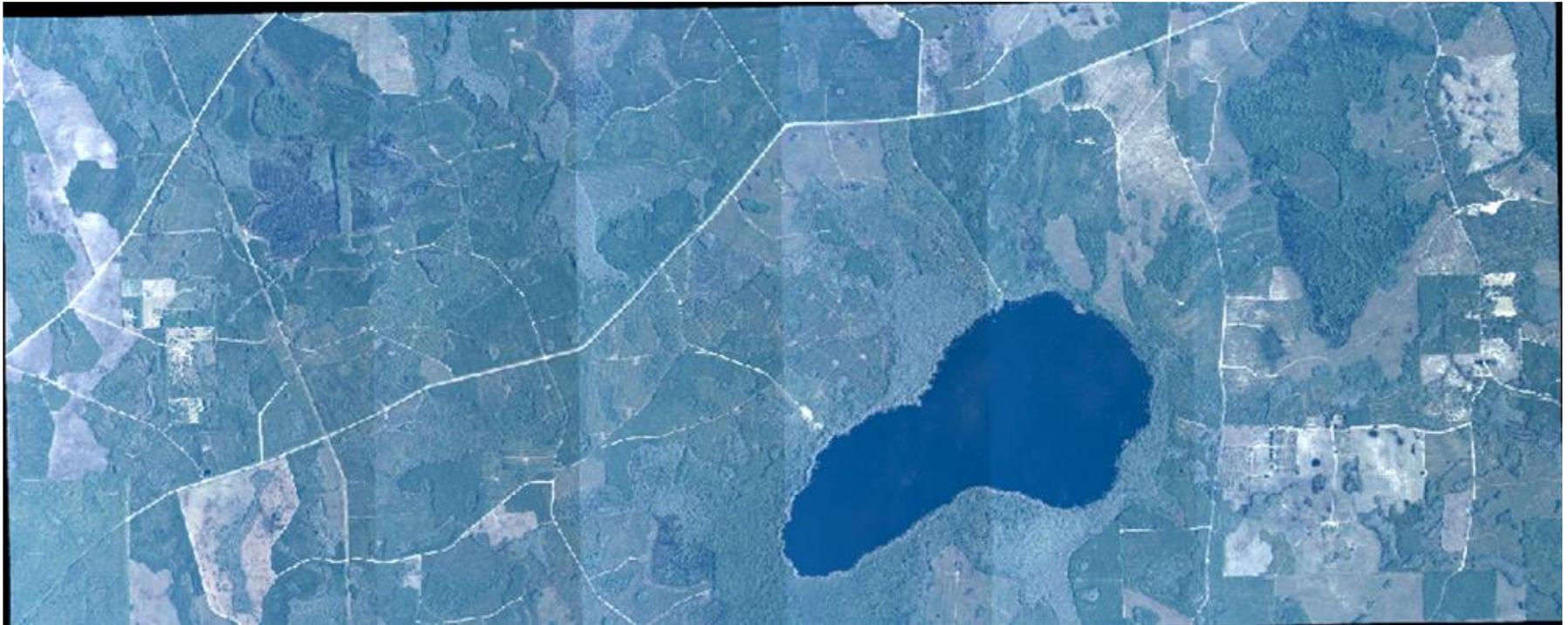


Laboratory Calibration

- ▶ Absolute Radiometric Calibration
 - Convert image DN's into physical units
 - Requires spectral response measurement



Significant Haze Example



Intermediate color
corrected images

DMCII-250 single flight line (6 images)
Baker County, FLA
~6,000 m
Pan-sharpened Overview Level 2 Mosaic

Haze Reduction – Dark Pixel Subtraction Algorithm

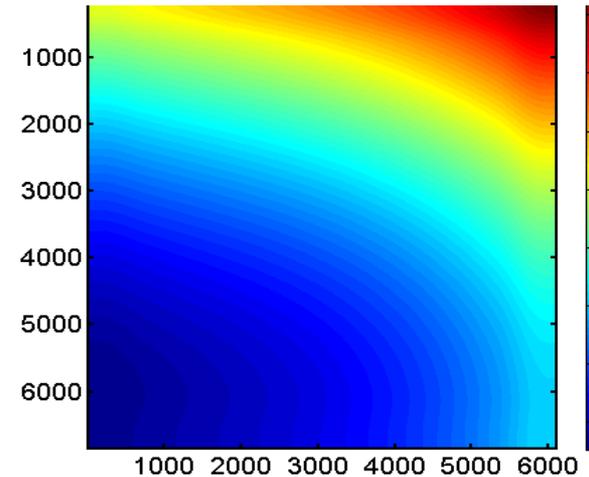
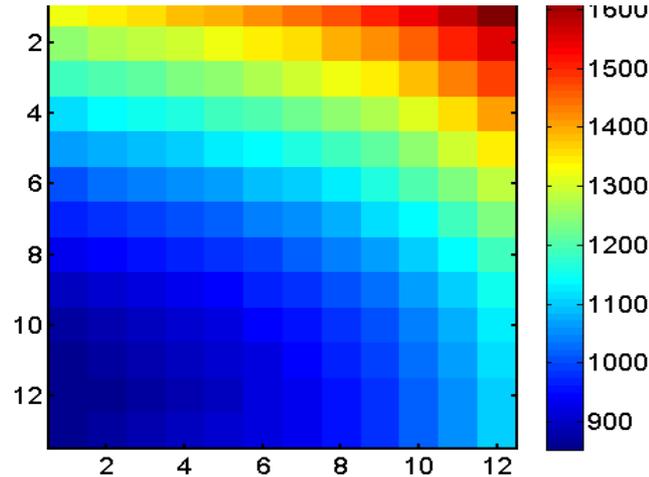
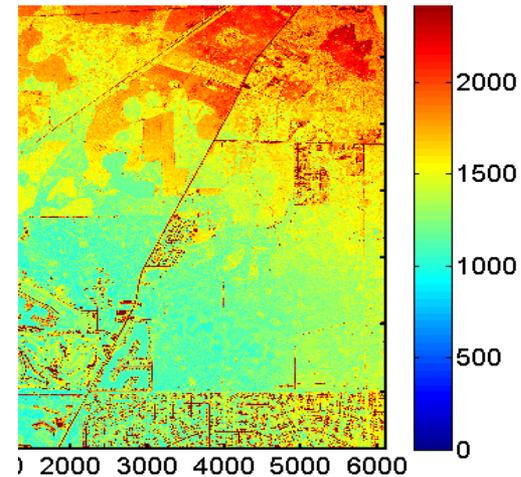
- ▶ Dark pixels are located throughout each image within $n \times n$ pixel grids
 - 512 x 512 grid for multispectral bands
 - 1024 x 1024 grid for pan band
 - A water mask and other criteria are applied to locate deep dark shadowed land areas
- ▶ A reflectance value is assigned to each dark pixel
- ▶ The remaining signal is assumed to be haze and is subtracted from each pixel within an image

Example Dark Pixel Subtraction

Input Image
(Blue Band)

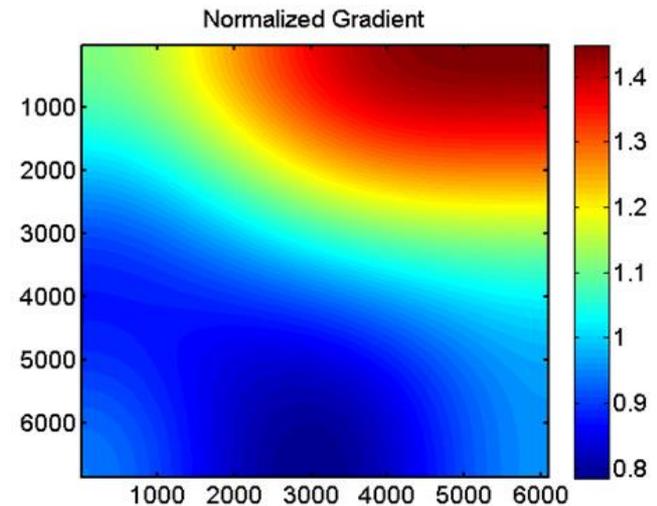
Dark Pixel Grid

Interpolated Dark
Pixel Values



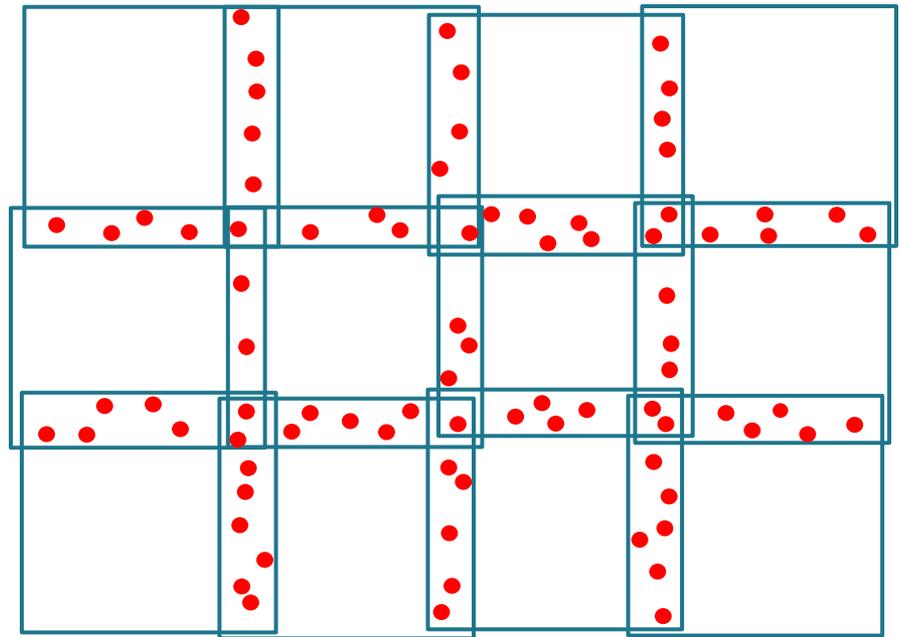
Gradient Effects

- ▶ Algorithm removes/reduces any remaining gradient across the image
 - General land cover classification is performed
 - Gradient statistics are collected based on land cover type
 - Multiple images are needed to acquire enough statistics per land cover
 - Algorithm utilizes a physics-based model with statistically based image information
 - Resulting gradient model is applied to each dark pixel subtracted image



Radiometric Triangulation

- ▶ Block-wise Normalization
 - Utilize radiometric information from multiple images within a block to generate a uniform color collection of images
 - Employ tie points
 - Least squares model
- ▶ Goal is to *significantly* reduce the workflow associated with generating ortho-mosaics



Sample Mosaic – Brandenburg, Germany

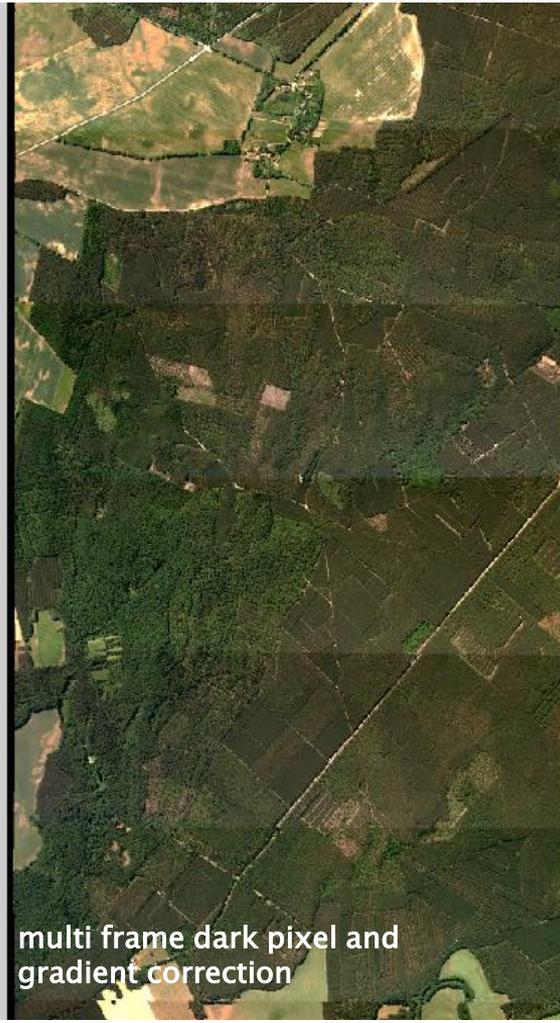
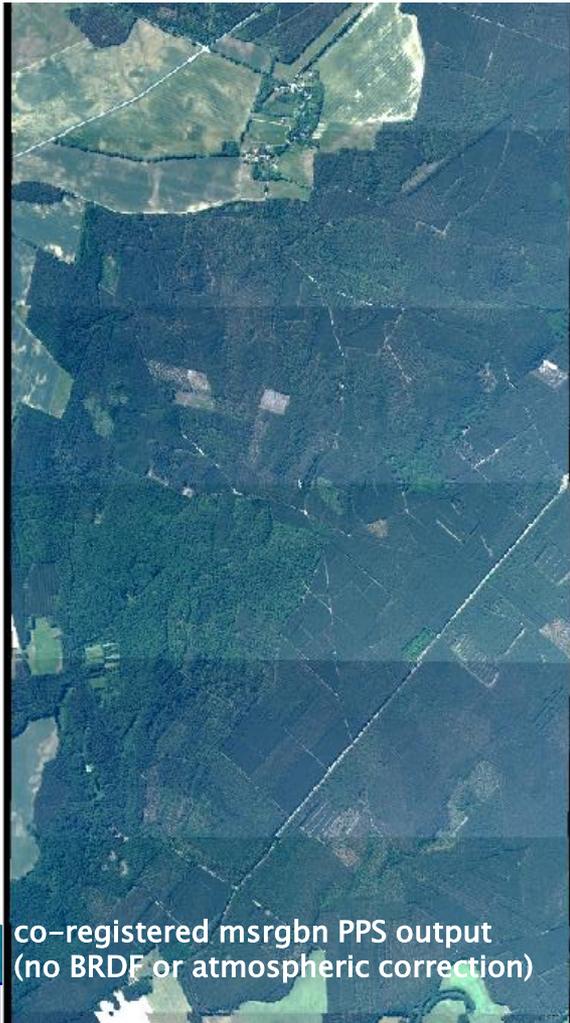
DMCII 230 Imagery at 3.2km Altitude



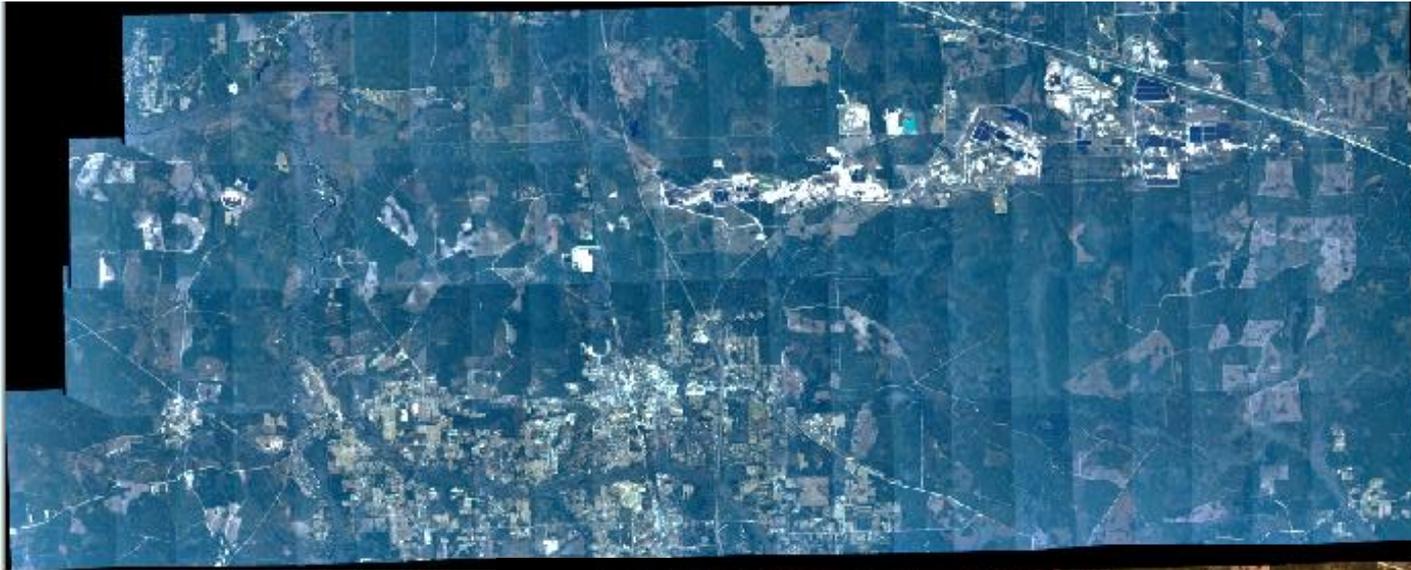
Low Altitude, High Haze example
40 frames/1 line

Sample Mosaic – Brandenburg, Germany

DMCII 230 Imagery at 3.2km Altitude



Sample Mosaic - Baker County, Florida DMCII 250 Imagery at 6.0 km Altitude



High Altitude,
High Haze example
84 frames/4 lines



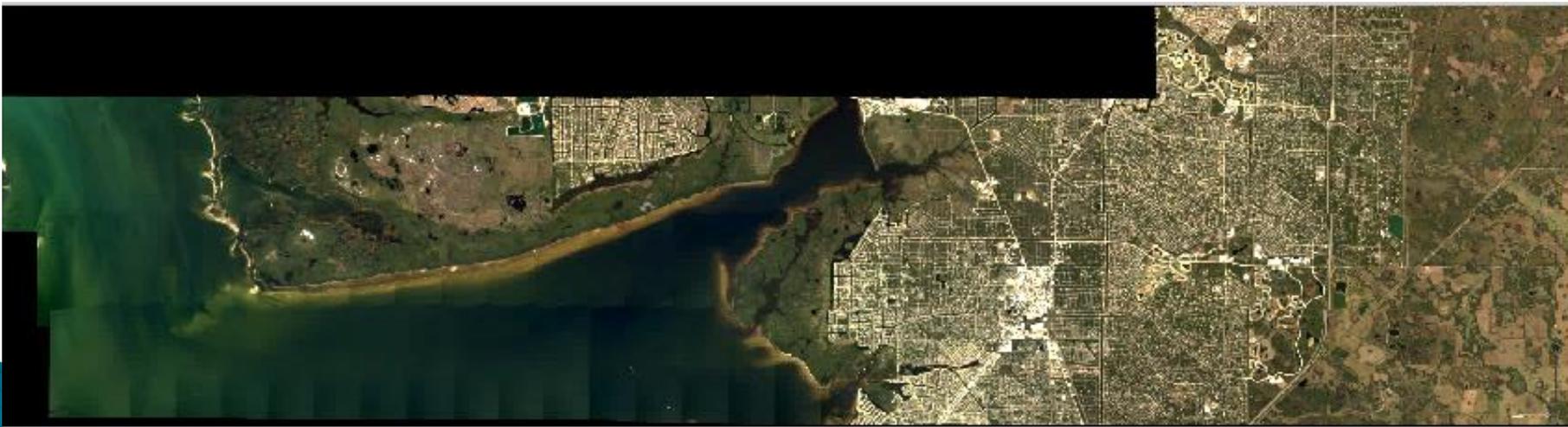
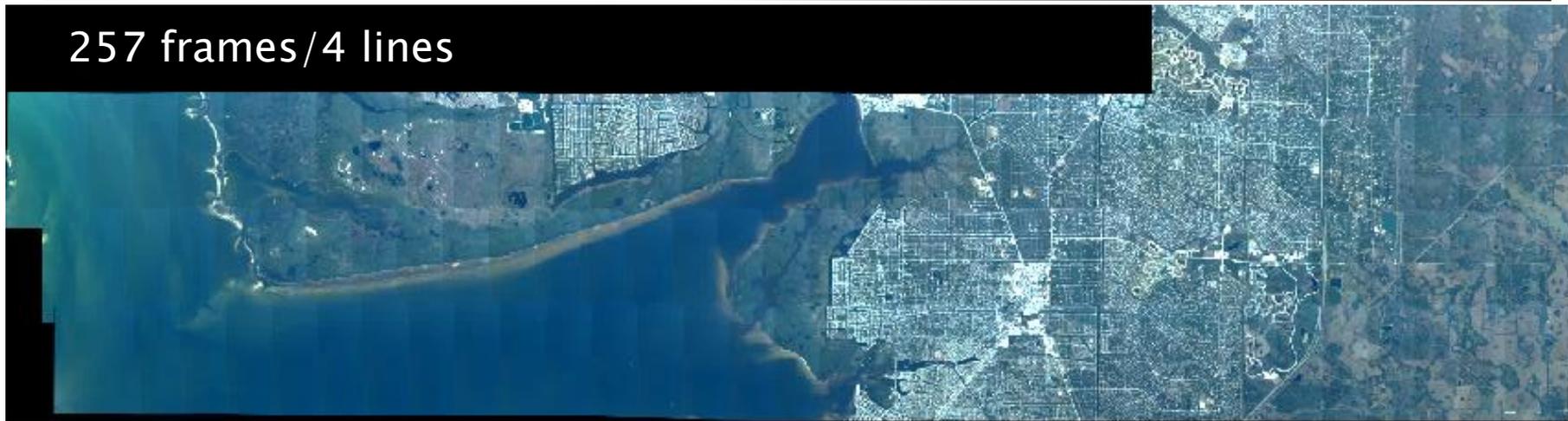
Sample Mosaic – Baker County, Florida DMCII 250 Imagery at 6.0 km Altitude



Sample Mosaic - Tampa, Florida

DMCII 250 Imagery at 6.0 km Altitude

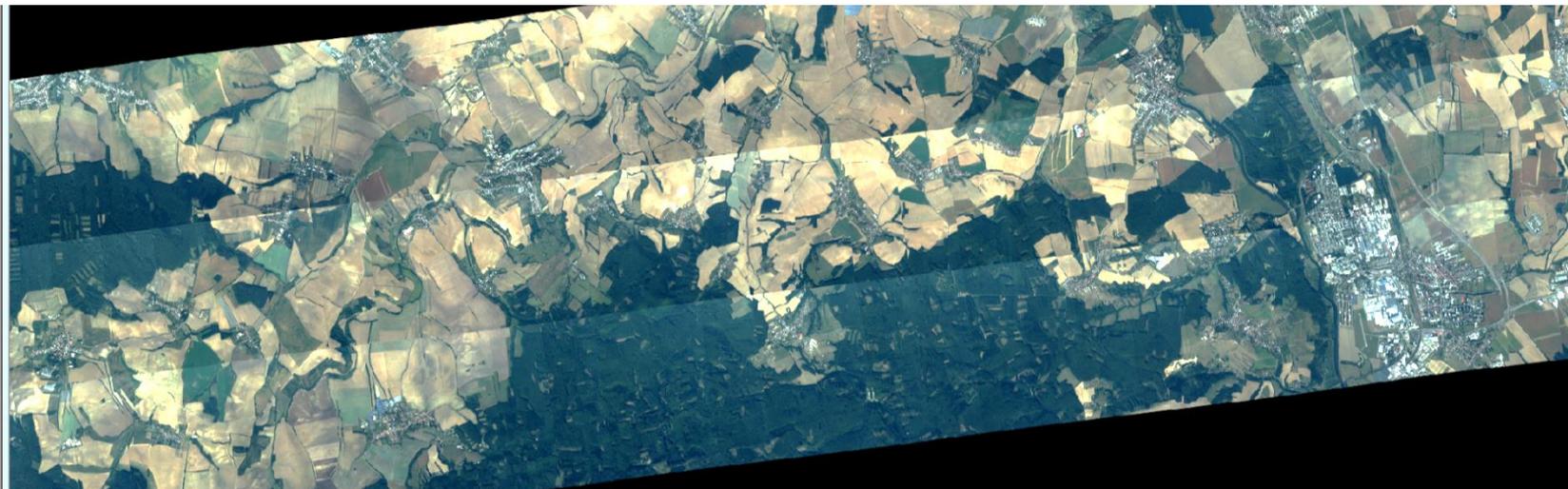
257 frames / 4 lines



Sample Mosaic – Misawa, Japan DMCII 140 Imagery at 1.5 km Altitude

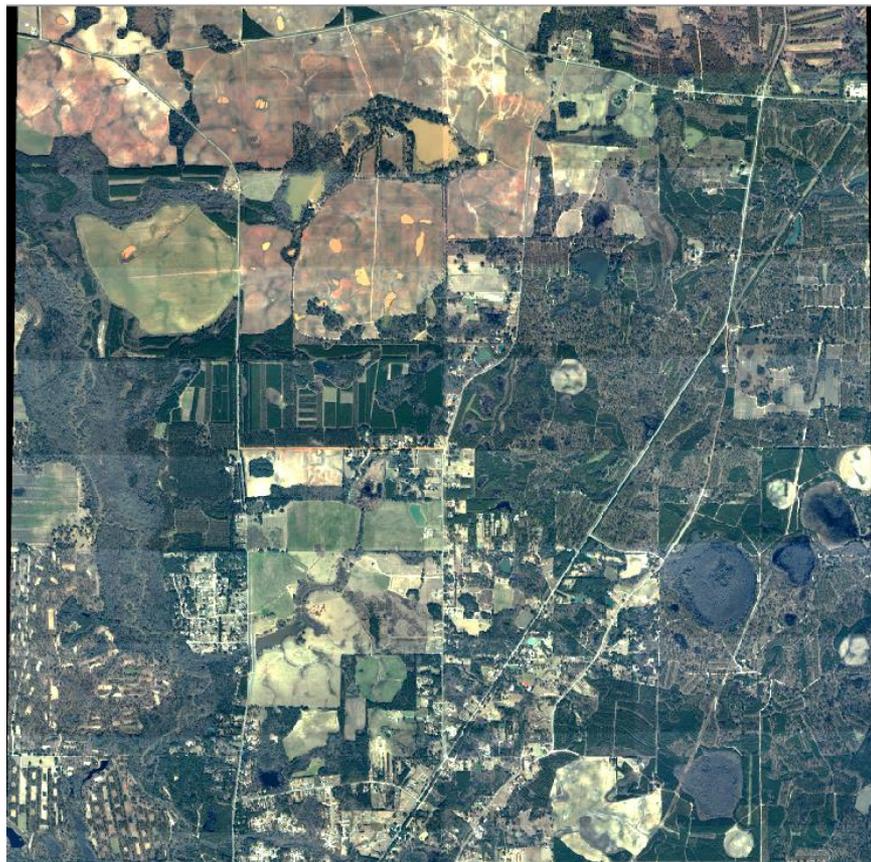


Sample Mosaic -Germany DMCII 250 Imagery at 4.0 km Altitude



170 frames, 3 lines
Hazy atmosphere

Sample Mosaic – Southwest Georgia DMCII 250 Imagery at 6.0 km Altitude



High Altitude, High Haze
Urban/vegetation land cover example

Summary

- ▶ Careful attention to the radiometric workflow enables:
 - Color consistency between cameras
 - Automated atmospheric correction
 - Haze reduction / dark pixel subtraction
 - Gradient reduction
 - Automated high quality seamless mosaics

Acknowledgements and Thanks

- ▶ Image Providers
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